

# HySEA model

## Benchmark problems 1, 2, 3, 4 and 5

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# The HySEA model

## Plan for the presentation

- ① The HySEA model (in few words)
- ② (Previous) Validation
- ③ Benchmark 1 - SB4\_02 Lloyd & Stansby (1995)
- ④ Benchmark 2 - Hilo Harbour
- ⑤ Benchmark 3 - Tauranga Harbour
- ⑥ Benchmark 4 - Seaside (Oregon)
- ⑦ Benchmark 5 - Triangular shaped shelf with an island

# 1. The HySEA model

## A family of codes

- Non-linear Shallow Water Equations
- Structured and non-structures meshes (multiGPU)
- UTM and lat/lon coordinates (multiGPU)
- Weakly dispersive (MS model). Beta version.
- Two-Layer Savage-Hutter shallow water system (multiGPU)
- Shallow-Water Exner system on structured and non-structured meshes (bedload transport). GPU
- and others (turbidity currents, coupling biology and hidroynamics, multilayer,...)

## Simulating...

- Earthquake generated tsunamis (**tsunami-HySEA**)
- Submarine and aerial landslide generated tsunamis (**landslide-HySEA**)
- Sediment bedload transport
- Turbidity currents and sedimentary plumes
- Physical-biological coupled processes
- others

# 1. Tsunami-HySEA

Numerics: A family of Finite Volume numerical schemes

- **Scenarios:** WAF method (LW+HLL)<sup>1</sup> and higher order
- **TEWS:** hybrid 2s+WAF<sup>2</sup>
- **Laboratory experiments:** higher order methods
- Wet/Dry front treatment<sup>3,4,5</sup>
- Nested meshes and/or AMR (GPU)

<sup>1</sup> **de la Asunción et al. (2012).** Efficient GPU implementation of a two waves TVD-WAF method for the two-dimensional one layer shallow water system on structured meshes, *Computers & Fluids*.

<sup>2</sup> Article in progress

<sup>3</sup> **Castro, González-Vida, Parés (2005).** Numerical treatment of wet/dry fronts in shallow water flows with a modified Roe scheme. *Math. Mod. and Meth. in Applied Sci.*

<sup>4</sup> **Gallardo, Parés, Castro (2007).** On a well-balanced high-order finite volume scheme for shallow water equations with topography and dry areas. *J. Comput. Phys.*

<sup>5</sup> **Castro, Fernández, Ferreiro, García, Parés (2009).** High order extensions of Roe schemes for two dimensional nonconservative hyperbolic systems. *J. Sci. Comput.*

# 1. Tsunami-HySEA

Numerics: A family of Finite Volume numerical schemes

- **Scenarios:** WAF method (LW+HLL)<sup>1</sup> and higher order
- **TEWS:** hybrid 2s+WAF<sup>2</sup>
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- Nested meshes and/or AMR (GPU)

Nice properties

- Well-balanced (avoid spurious oscillations)
- Transitions from sub to super critical situations (arrival to coast)
- Positivity (no negative layer thickness)
- Inundation area and runup heights are model outputs
- Discontinuities in data or solutions (no need to smooth bathymetry)

Implementation

- CUDA - GPU/Multi-GPU (**very short computing times**)

# The HySEA model. Validation

## NOAA benchmarks (Synolakis et al., 2008)<sup>1</sup>

- **Analytical solutions**

- Single wave on a simple beach
- Solitary wave on composite beach
- Subaerial landslide on simple beach

- **Laboratory benchmarking**

- Solitary wave on a simple beach
- Solitary wave on a composite beach
- Solitary wave on a conical island
- Tsunami runup onto a complex three-dimensional beach. Monai Valley
- Tsunami generation and runup due to three-dimensional landslide

- **Field benchmarking**

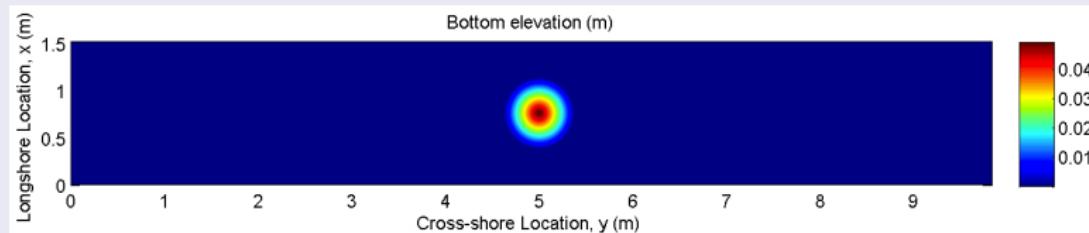
- Okushiri Island
- Rat Islands tsunami

<sup>1</sup> Millán (2014). Estudio y validación de un modelo de volúmenes finitos TVD-WAF 2D de aguas someras para la simulación de tsunamis. *Universidad de Málaga*, 101 pages.

# Benchmark Problem 1

## Setup

- Test case SB4\_02 in Lloyd and Stansby (1995) Part II
- Steady discharge  $U=0.115 \text{ m/s}$
- Water depth  $h=0.054 \text{ m}$
- Reynolds number  $Re = 6210$
- Ratio water depth to island height  $h/h_i = 1.10$
- Bathymetry

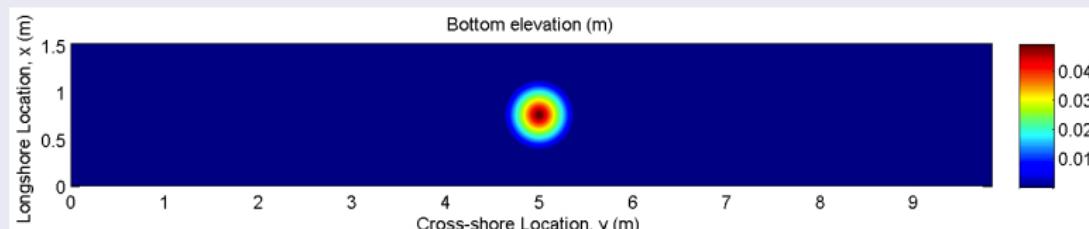


- Domain:  $[0, 9.75(84)] \times [0, 1.52]$
- Resolution:  $\Delta x = \Delta y = 0.0152 \text{ m}$
- Mesh:  $642 \times 100$

# Benchmark Problem 1. What we have done

## Numerical Experiments (112)

- **Order of the method:** 1<sup>st</sup>, 2<sup>nd</sup> and 3<sup>rd</sup>
- **Friction law:**
  - Quadratic (reference value  $c_f = 0.006$ )
  - Manning ( $M_n = 0.01$ )
- **Friction coefficient:** inviscid, 0.005 to 0.015 (step 0.001) - 12 cases -
- **3 Boundary conditions** (different implementations of the same BC)
  - ghost cells
  - 1 sponge layer<sup>1</sup>
  - 2 sponge layer<sup>1</sup>



<sup>1</sup> [Lavelle and Thacker \(2008\)](#). Ocean Modelling.

# Benchmark Problem 1

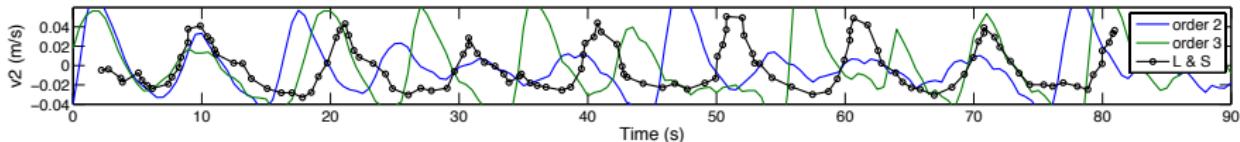
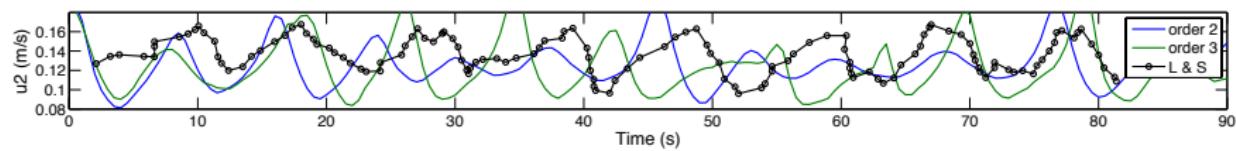
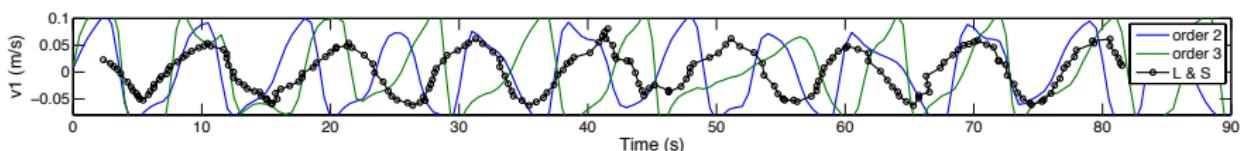
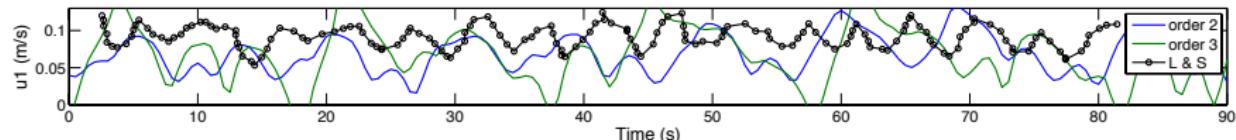
## Some comments

- Extremely sensitive problem
- 1<sup>st</sup> order too diffusive (refinement?)
- Any perturbation not leaving the domain will highly interfere the solution

# Benchmark Problem 1 - Boundary Condition 1

**Configuration 1. Cuadratic friction with  $C_f = 0.006$**

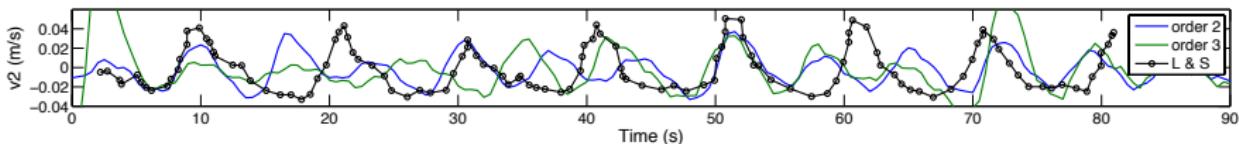
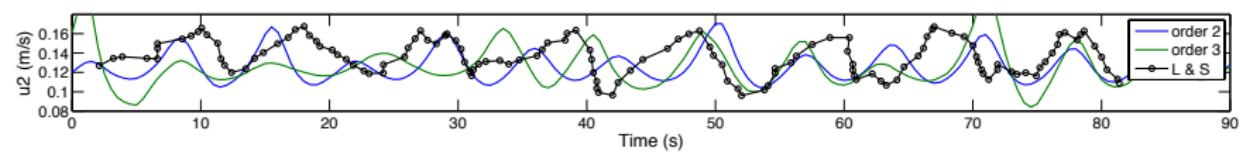
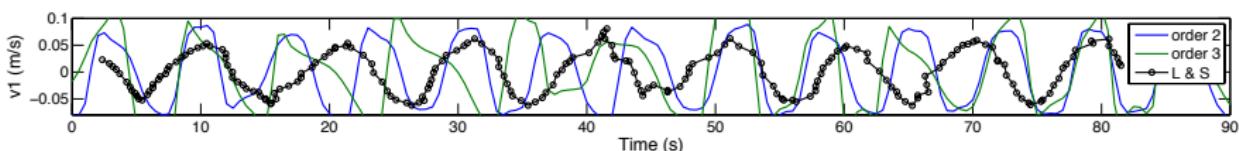
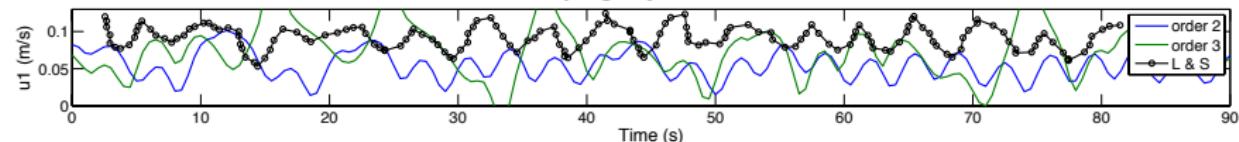
0 sponge layers –  $c=0.006$



# Benchmark Problem 1 - Boundary Condition 2

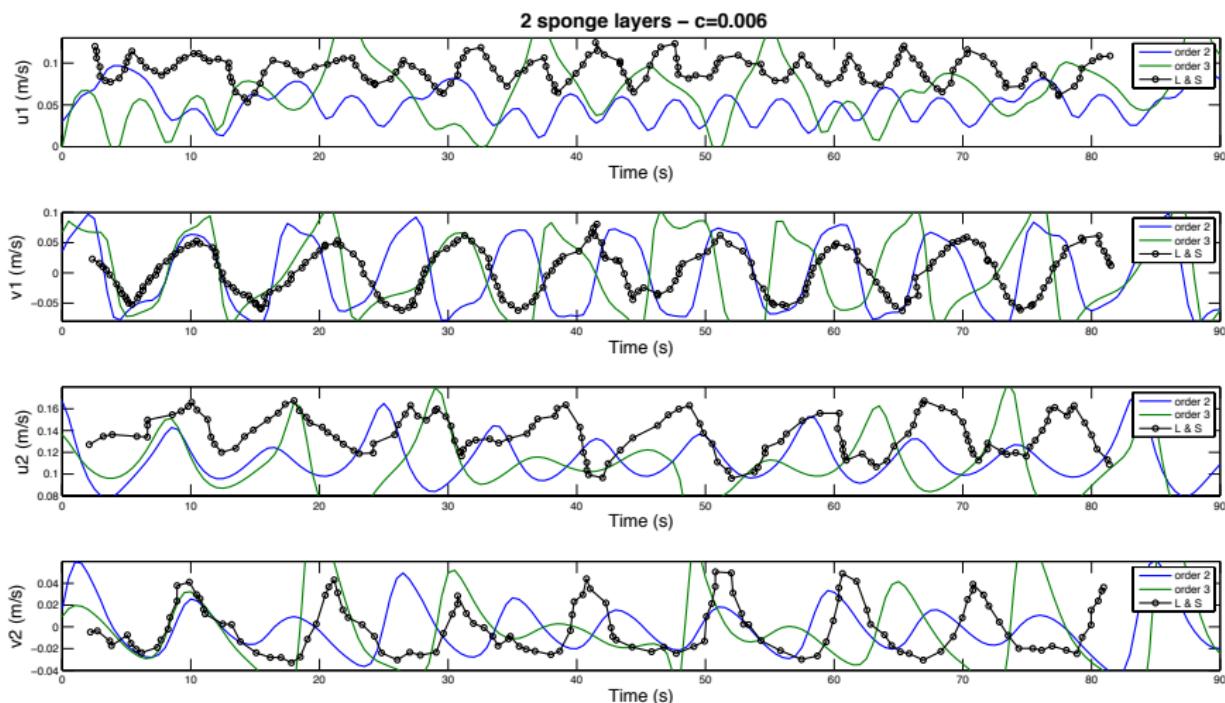
**Configuration 1. Quadratic friction with  $C_f = 0.006$**

1 sponge layer –  $c=0.006$



# Benchmark Problem 1 - Boundary Condition 3

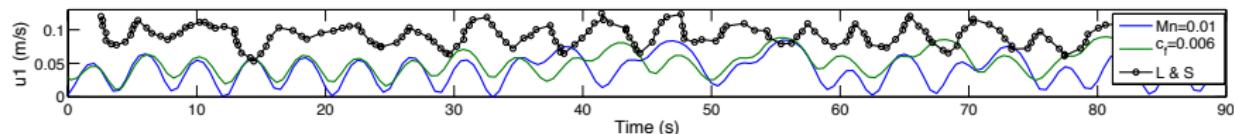
**Configuration 1. Cuadratic friction with  $C_f = 0.006$**



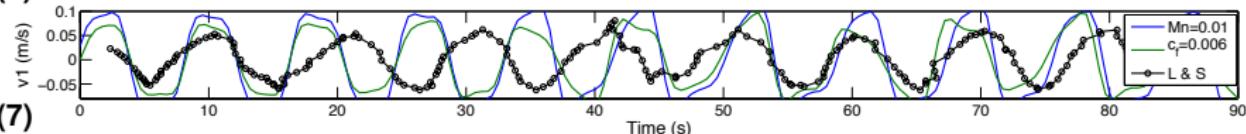
# Benchmark Problem 1 - Boundary Condition 3

**Configuration 1. Quadratic friction with  $C_f = 0.006$  and Manning  $M_n = 0.01$**

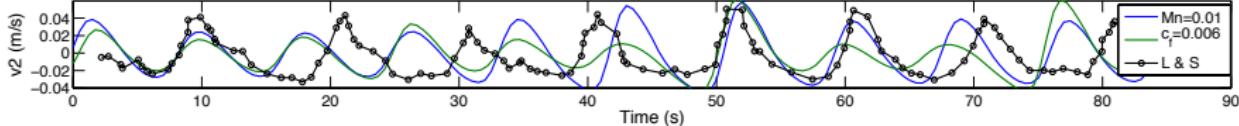
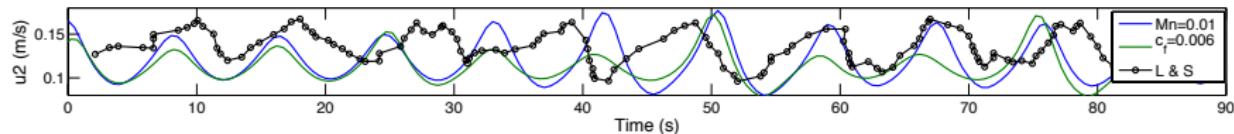
Order 2 – BC3 – Manning=0.01 –  $c_f=0.006$



7 (6)



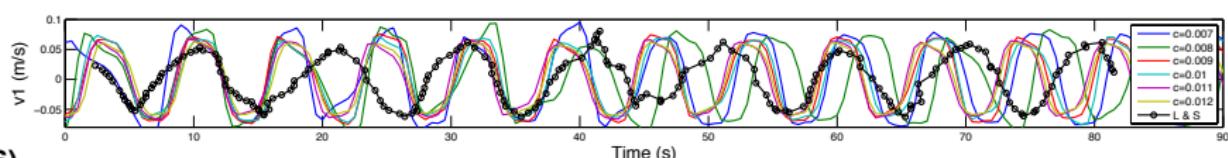
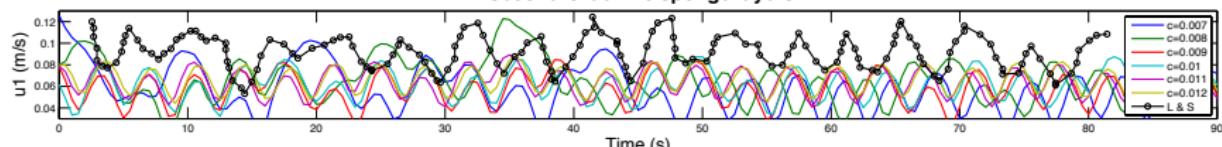
8 (7)



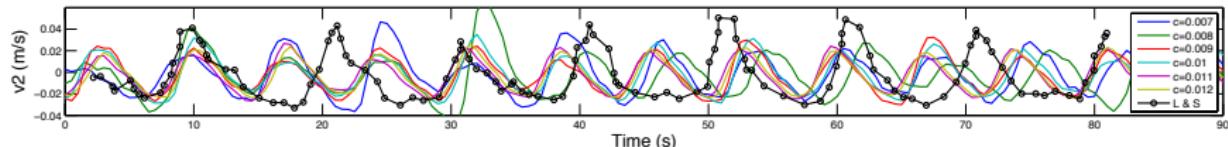
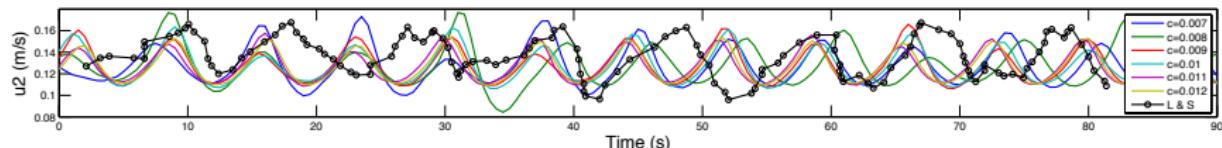
# Benchmark Problem 1 - Boundary Condition 1 - 2<sup>nd</sup> order

## Configuration 2. Looking for the optimized friction

Second Order – 0 sponge layers



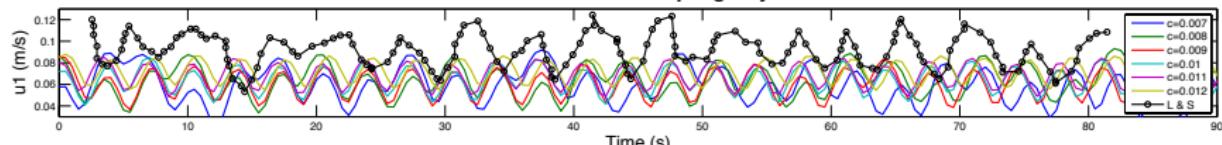
8 (6)



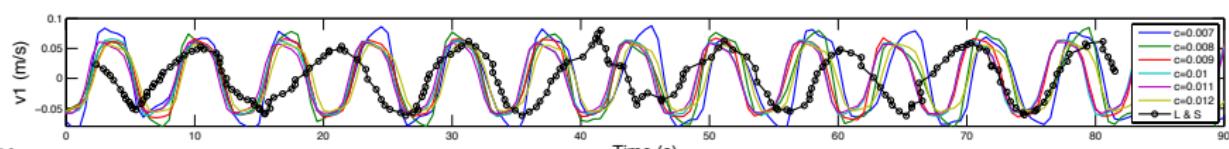
# Benchmark Problem 1 - Boundary Condition 2 - 2<sup>nd</sup> order

## Configuration 2. Looking for the optimized friction

Second Order – 1 sponge layer

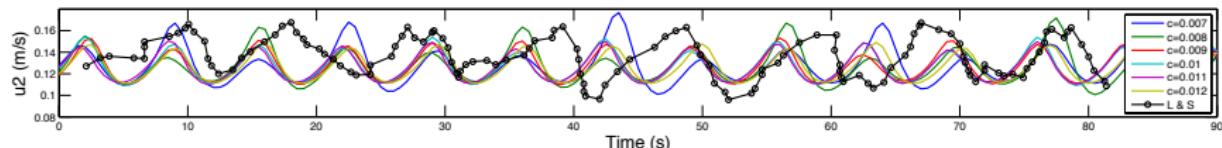


Time (s)

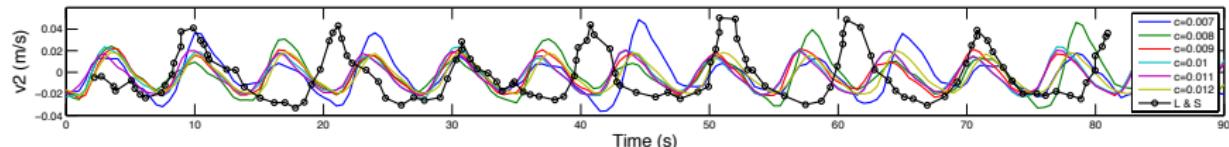


Time (s)

8 (6)



Time (s)

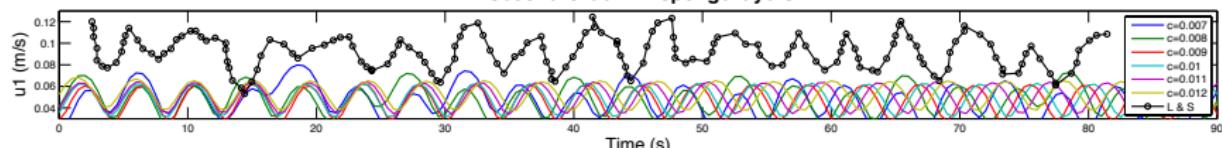


Time (s)

# Benchmark Problem 1 - Boundary Condition 3 - 2<sup>nd</sup> order

## Configuration 2. Looking for the optimized friction

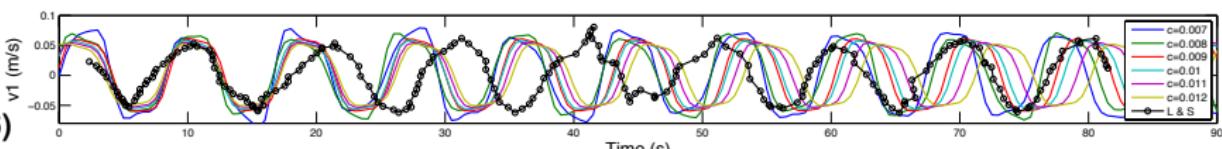
Second Order – 2 sponge layers



7 (6)

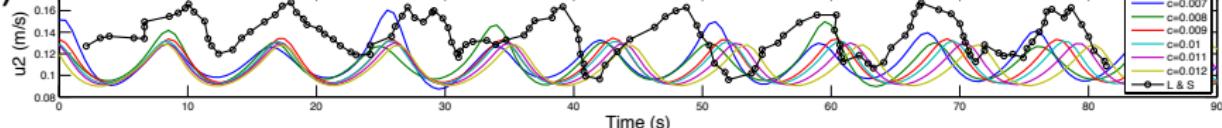
Time (s)

$v_1$  (m/s)



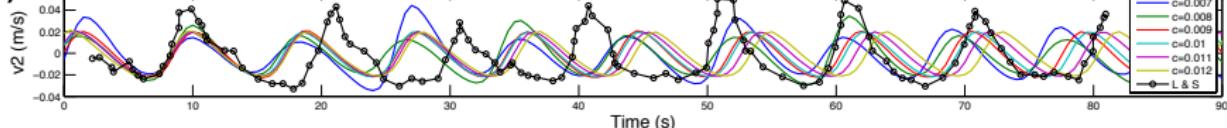
8 (7)

Time (s)



7 (6)

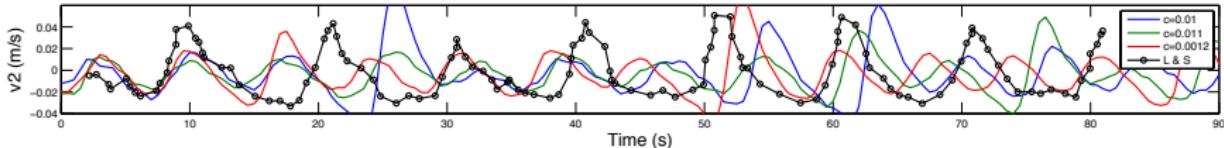
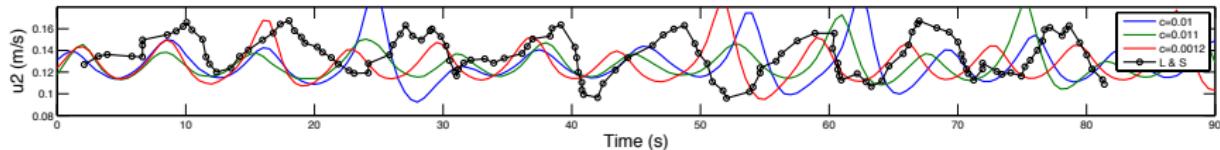
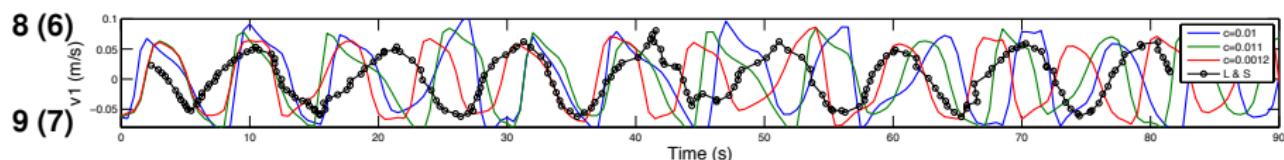
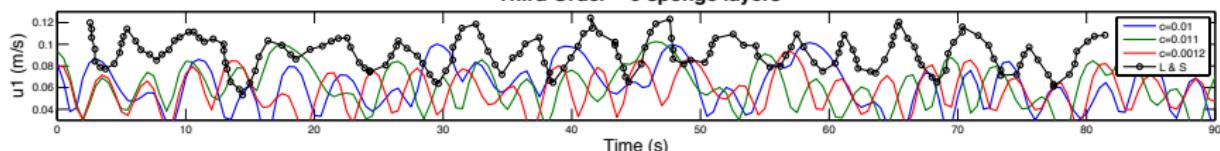
Time (s)



# Benchmark Problem 1 - Boundary Condition 1 - 3<sup>rd</sup> order

## Configuration 2. Looking for the optimized friction

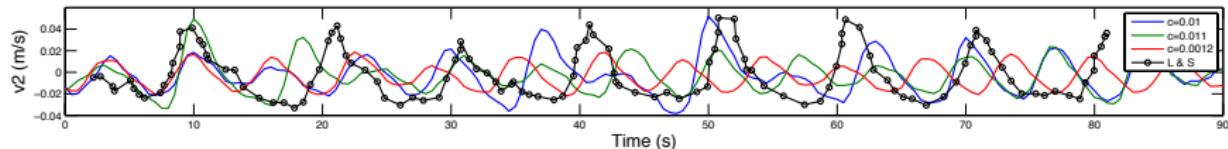
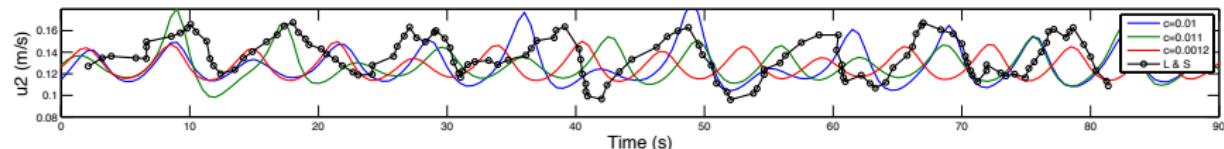
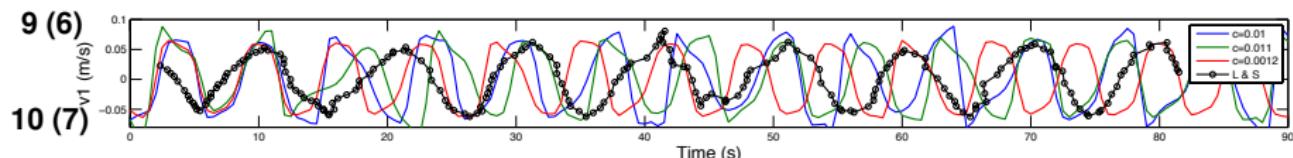
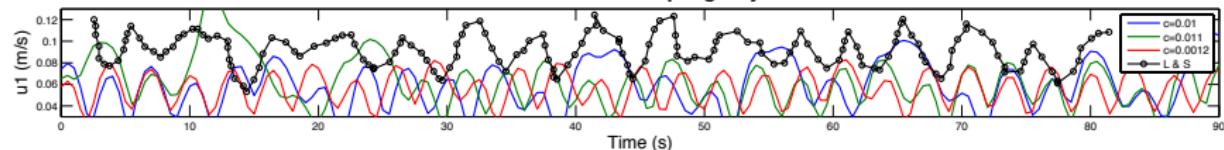
Third Order – 0 sponge layers



# Benchmark Problem 1 - Boundary Condition 2 - 3<sup>rd</sup> order

## Configuration 2. Looking for the optimized friction

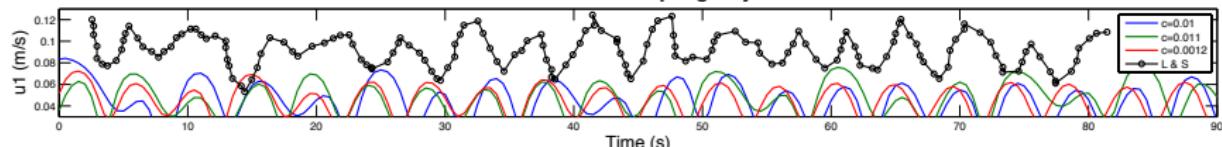
Third Order – 1 sponge layer



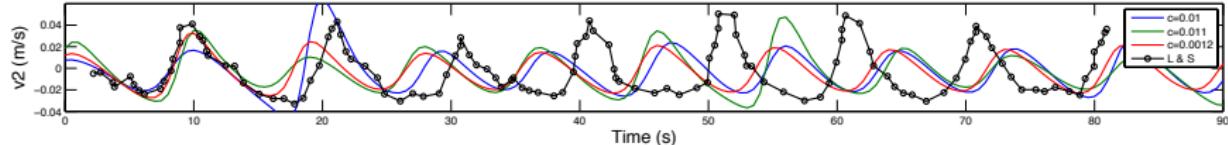
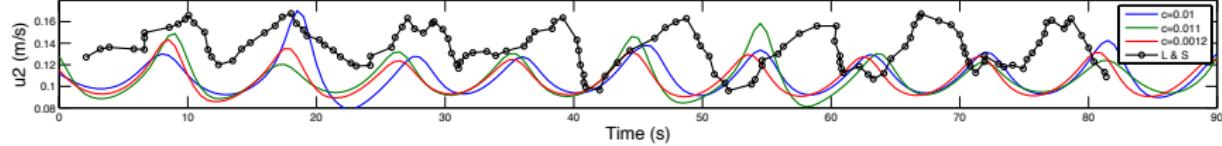
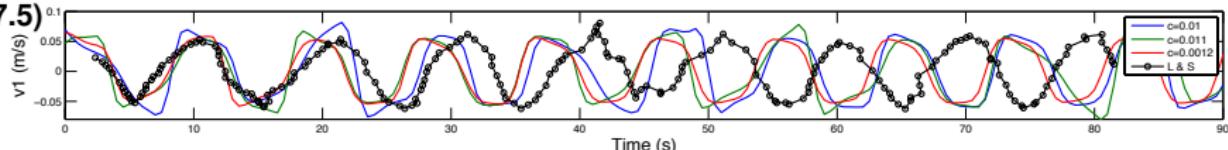
# Benchmark Problem 1 - Boundary Condition 3 - 3<sup>rd</sup> order

## Configuration 2. Looking for the optimized friction

Third Order – 2 sponge layers



8 (7.5)

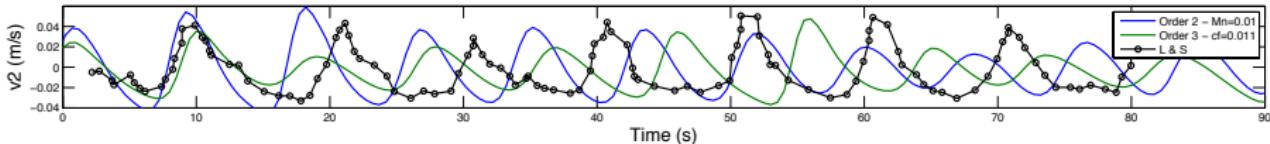
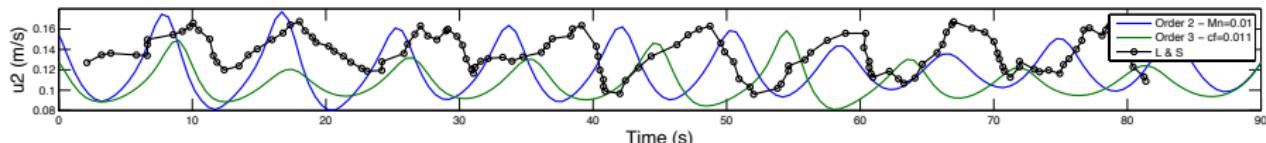
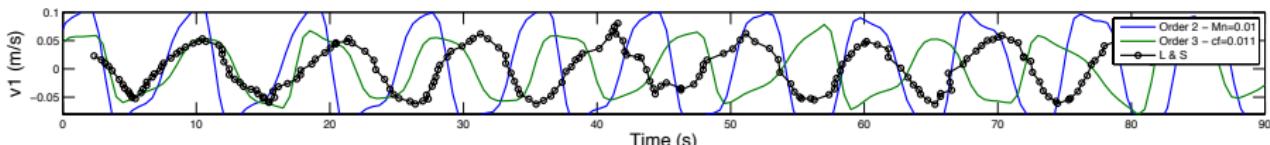
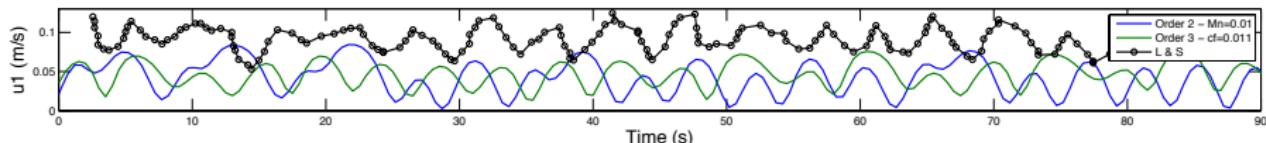


# Benchmark Problem 1 - Optimal choice

Just to make an “optimal” choice:

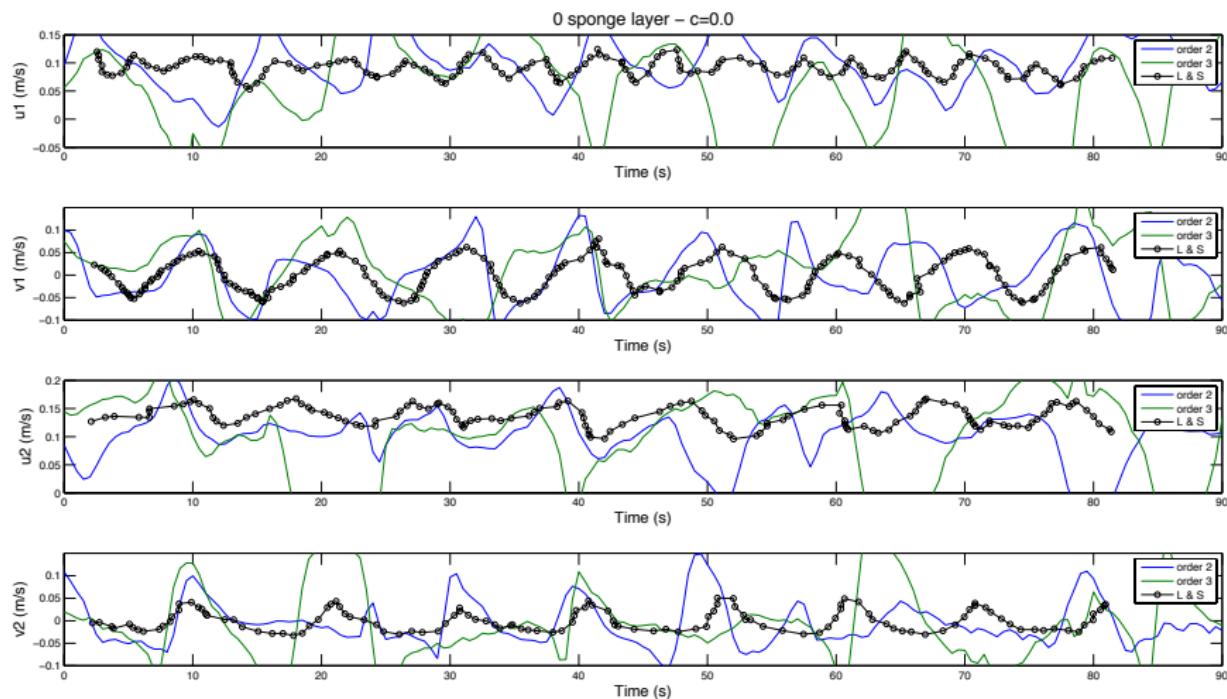
- Amplitude: Order 2 - BC3 -  $M_n = 0.01$
- Frequency: Order 3 - BC3 -  $c_f$  various (0.01)

Optimal – Order 2 and 3 – BC3 – Manning=0.01 –  $c_f=0.011$



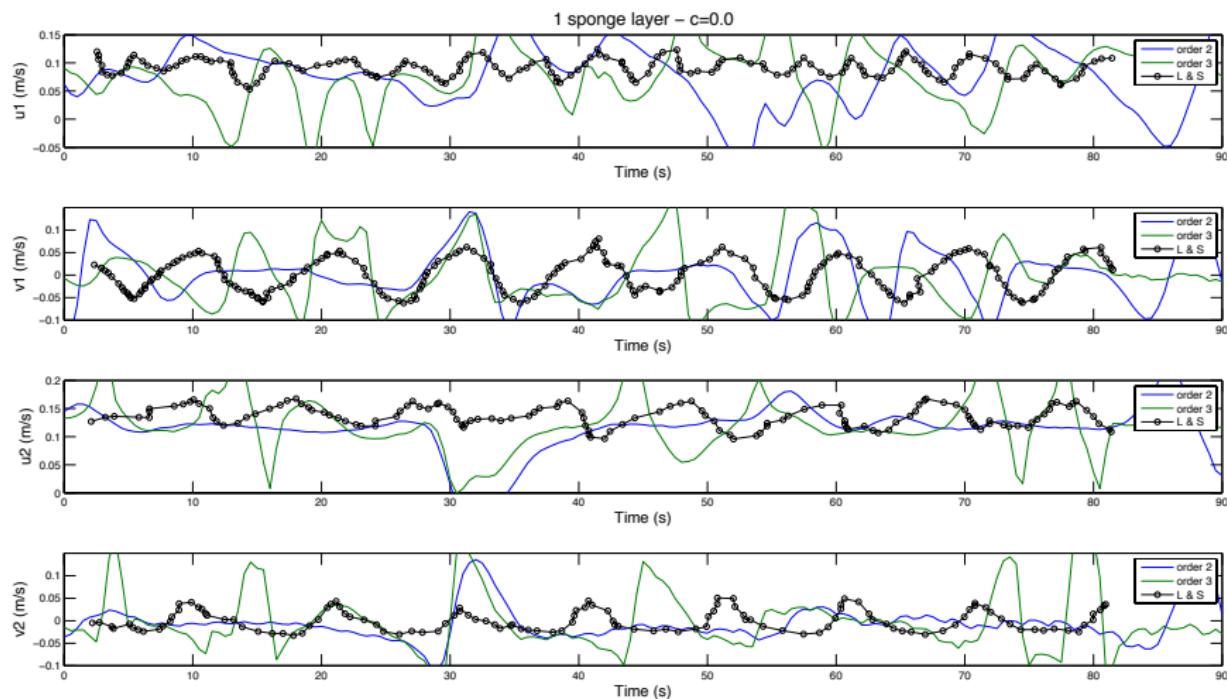
# Benchmark Problem 1 - Boundary Condition 1

## Configuration 3. Inviscid



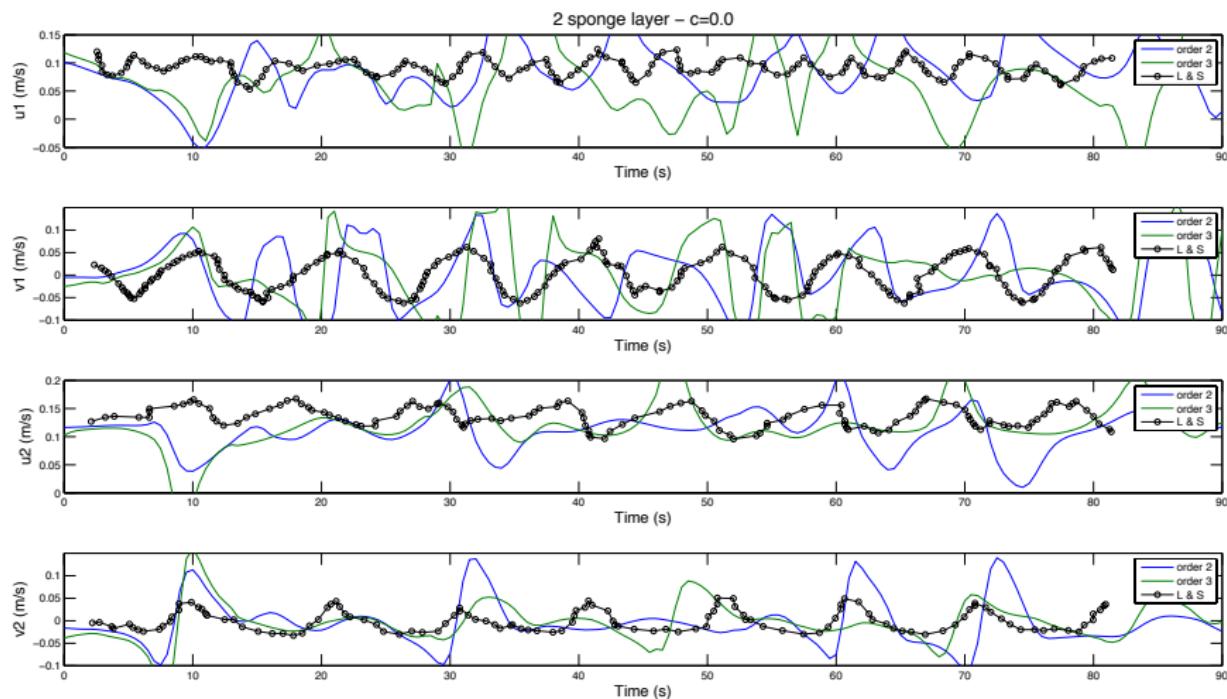
# Benchmark Problem 1 - Boundary Condition 2

## Configuration 3. Inviscid



# Benchmark Problem 1 - Boundary Condition 3

## Configuration 3. Inviscid



## Benchmark Problem 1 - Conclusions

### About the order

- Forget about 1<sup>st</sup> order (at least for the given resolution  $\Delta x = 0.01$ )
- 3<sup>rd</sup> order not necessarily better (why?)
- Higher the order better the BC must do

### About the friction

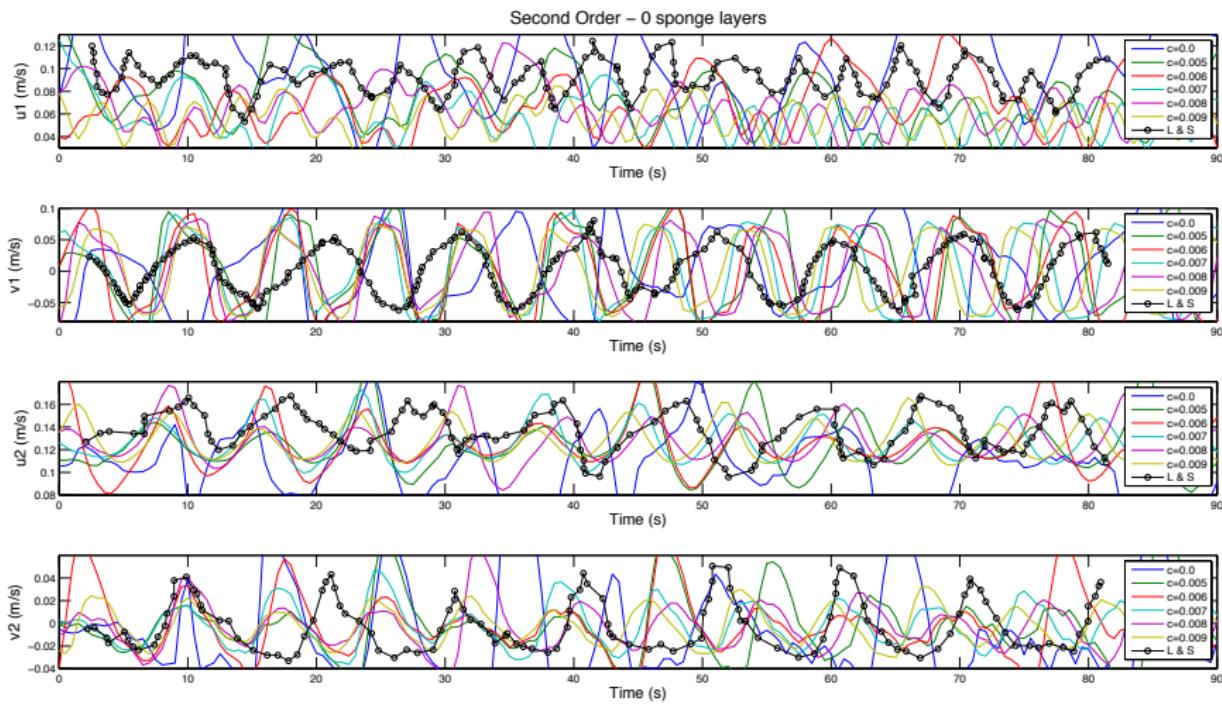
- High sensibility for low values
- Low sensibility for higher values
- Regular, periodic solutions for high friction values
- The better you do (order and BC), sensibility for higher values increases (frequency)

### About the BC

- The implementation of the BC is crucial
- So sensitive that perturbations must leave, if not ...
- But, disappointingly, no one it is the absolute better choice

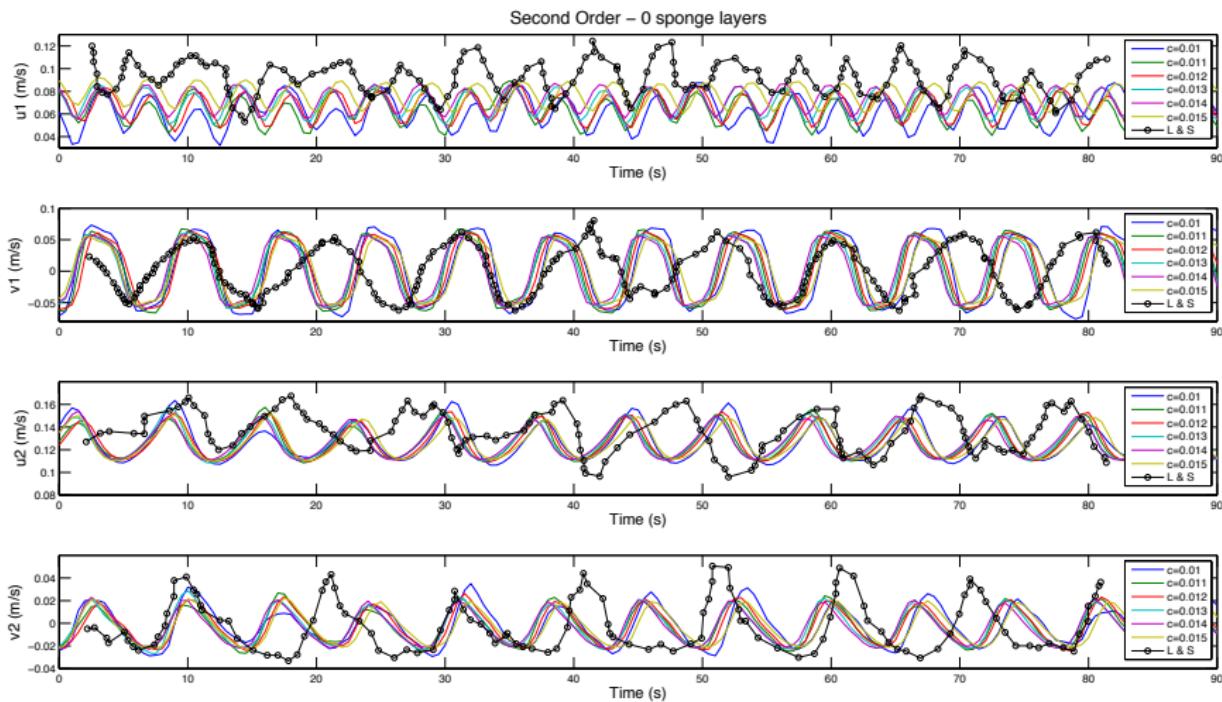
# Benchmark Problem 1 - Sensitivity to friction

High sensitivity to low values



# Benchmark Problem 1 - Sensitivity to friction

**Low sensitivity to high values**



## Benchmark Problem 1 - Conclusions

### About the order

- Forget about 1<sup>st</sup> order (with the given resolution  $\Delta x = 0.01$ )
- 3<sup>rd</sup> order not necessarily better (why?)
- Higher the order better the BC must do

### About the friction

- High sensibility for low values
- Low sensibility for higher values
- Regular, periodic solutions for high friction values
- The better you do (order and BC), sensibility for higher values increases
  - for 2<sup>nd</sup> order 2 sponge layers modify the frequency
  - 3<sup>rd</sup> order needs 2 sponge layers to homogenize the behaviour

### About the BC

- The implementation of the BC is crucial
- So sensitive that perturbations must leave, otherwise ...

### And finally

- Disappointedly, we do not have A better choice

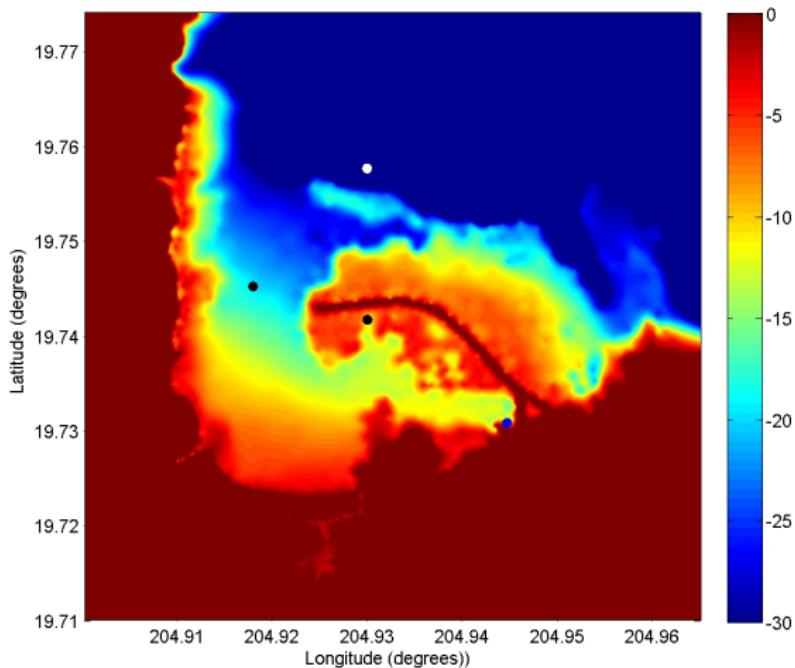
## Benchmark Problem 2 - Hilo Harbor

### Description and Aim

- **Field dataset** - Japan 2011 at Hilo Harbour (Hawaii)
- **Primary goal:** assess **model resolution** and **numerics** on the prediction of tsunami currents
  - Level of precision
  - Convergence (at least 3 resolutions:  $\approx 20$  m,  $\approx 10$  m and  $\approx 5$  m or lower)
  - Variation across different models

## Benchmark Problem 2 - Hilo Harbor

### Setup - Bathymetry



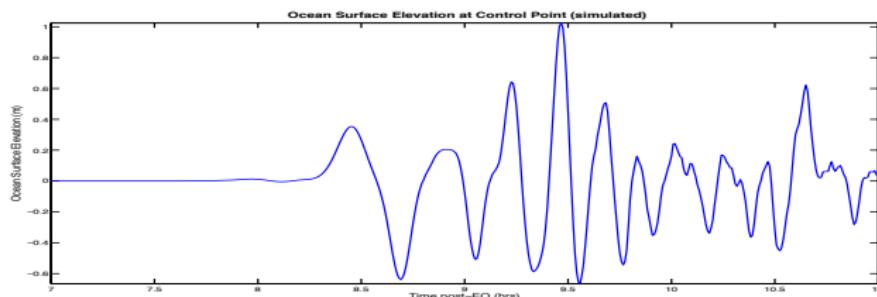
## Benchmark Problem 2 - Hilo Harbor

### Setup

- Domain:  $[204.90, 204.96] \times [19.71, 19.773]$  (approx  $7 \times 7$  km)
- Data Resolution: 1/3 arcsec ( $\approx 10$  m)
- Mesh:  $692 \times 701$
- Max depth 30 m
- Manning coefficient  $n = 0.025$  (But also  $n = 0.030$  and  $0.035$ )

### Boundary Condition

- Offshore simulated free surface elevation
- Control point at (19.7576, 204.93)
- Modellers chose the forcing



## Benchmark Problem 2 - What we have done

### 1. **Reduced domain** simulations at different resolutions (aim of the benchmark)

- Three requested resolutions (2/3, 1/3 and 1/6 arcsec)
- Sensitivity to friction ( $n=0.025, 0.030,$  and  $0.035$ )

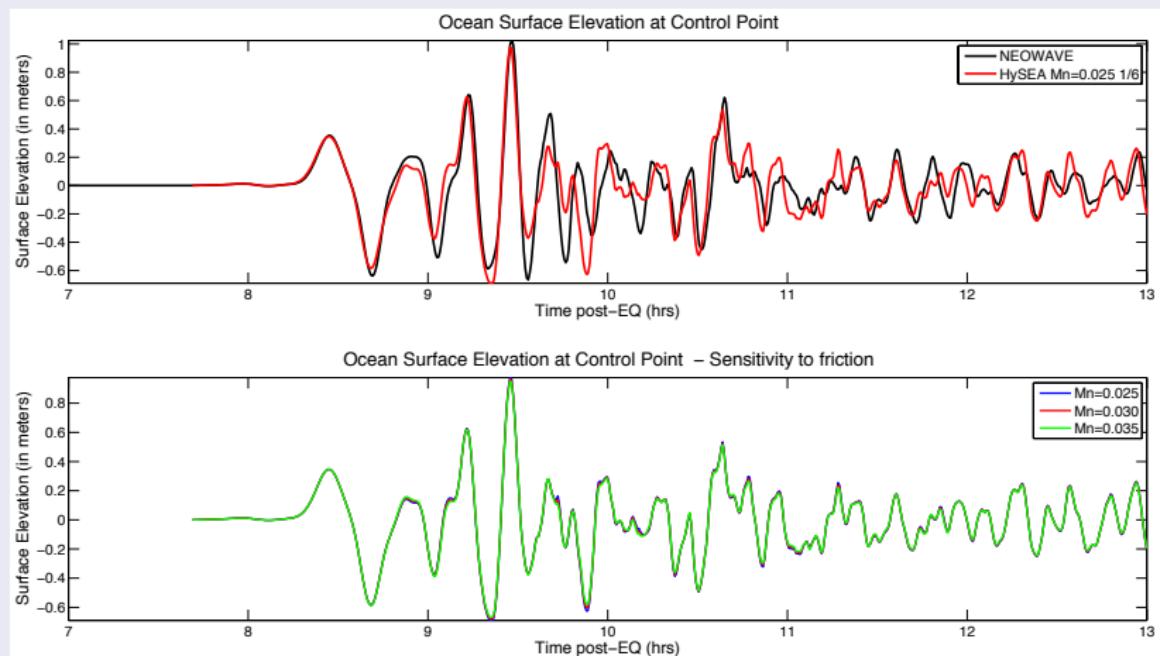
### 2. **Complete scenario** simulations at different resolutions (encouraged)

- Three level nested mesh decomposition
- Finer mesh of 2/3, 1/3 and 1/6 arcsec
- Varying coarse meshes

# Benchmark Problem 2 - Time series at control point

## 1. Comparison and Sensitivity to Friction

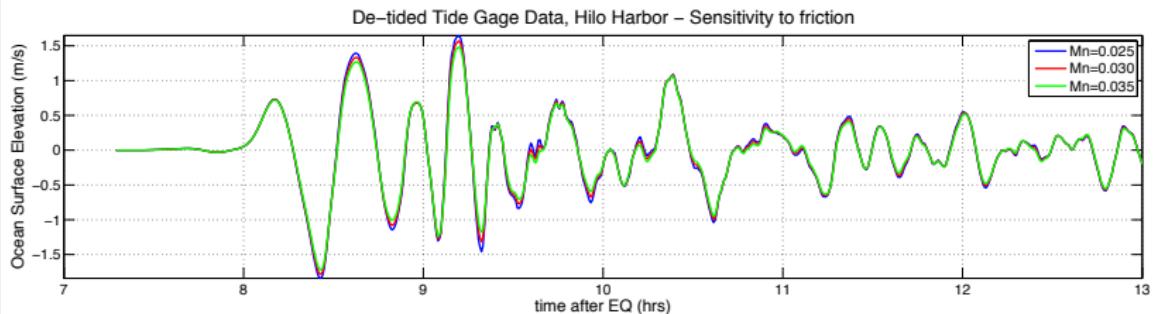
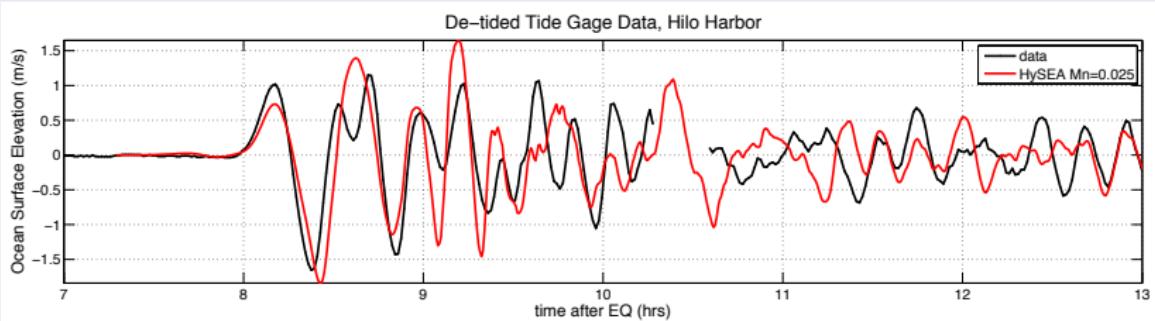
Control Point - [lat,lon] = (19.7576,204.93) - Res 1/6 - Mn=0.025



# Benchmark Problem 2 - Free surface elevation at the tidal station

## 1. Comparison and Sensitivity to Friction

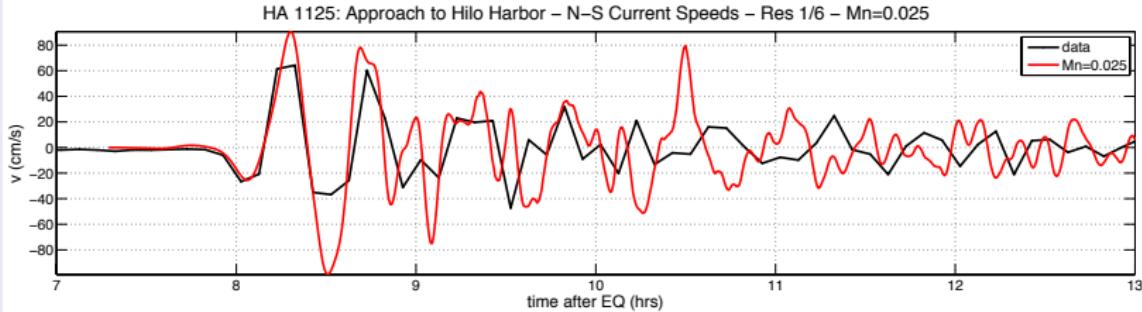
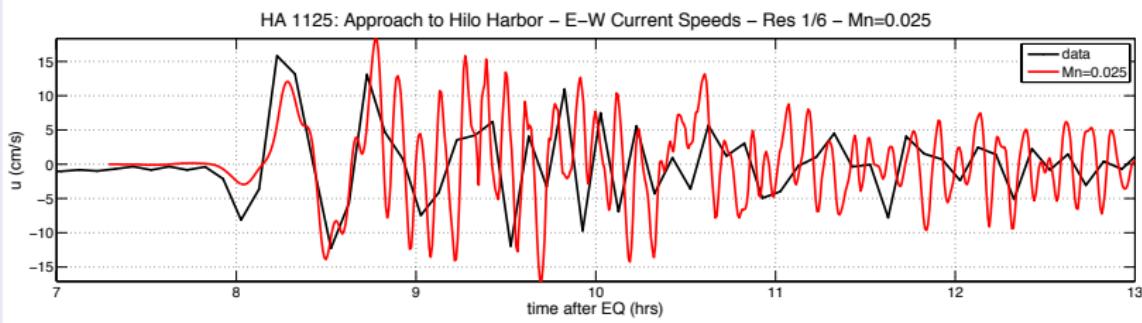
Hilo Tide Station - [lat,lon] = (19.7308,204.9447) - Res 1/6 - Mn=0.025



# Benchmark Problem 2 - Depth-average horizontal velocity data

## 1. Comparison

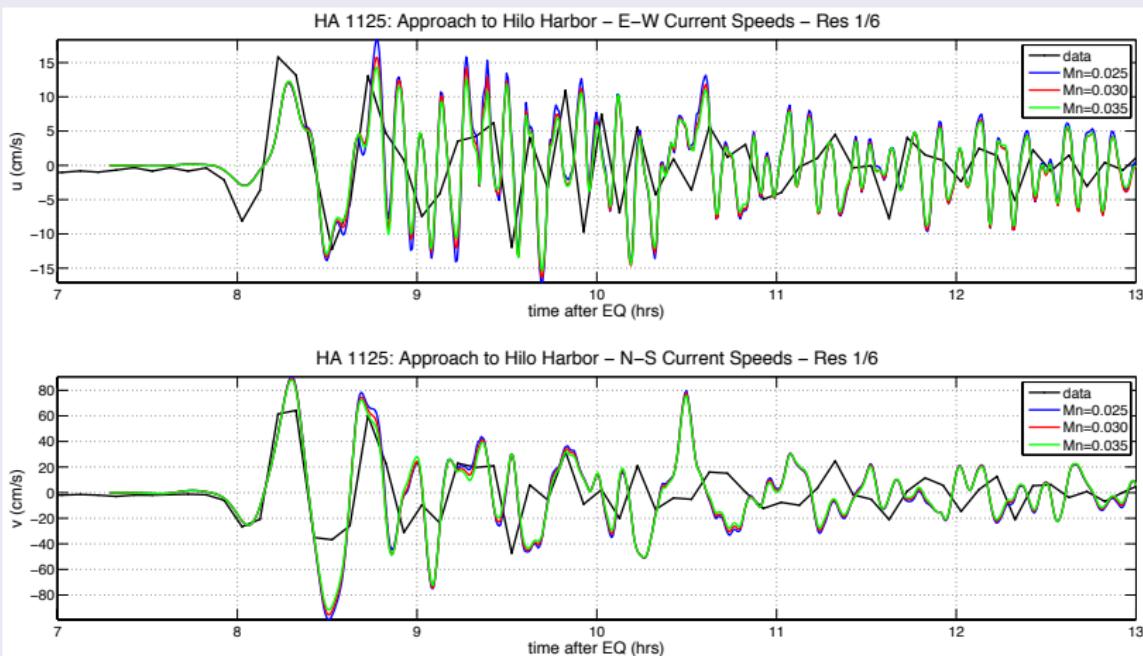
HA1125, Harbour entrance - [lat,lon] = (19.7452,204.9180) - Res 1/6



# Benchmark Problem 2 - Depth-average horizontal velocity data

## 1. Sensitivity to Friction

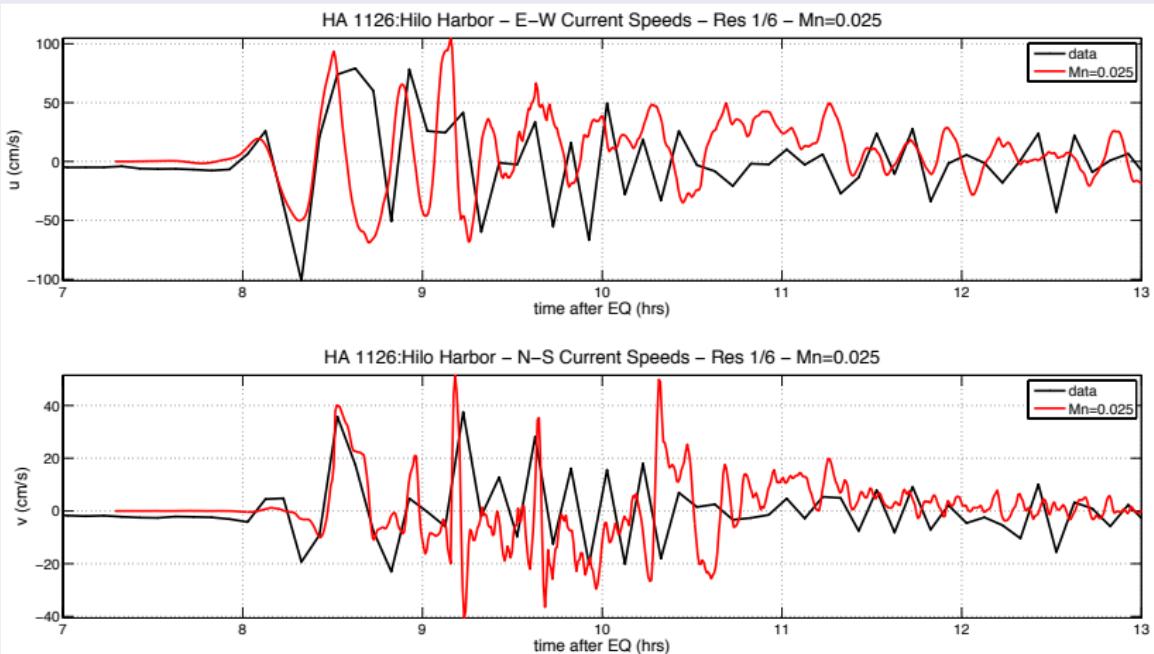
HA1125, Harbour entrance - [lat,lon] = (19.7452,204.9180) - Res 1/6



# Benchmark Problem 2 - Depth-average horizontal velocity data

## 1. Comparison

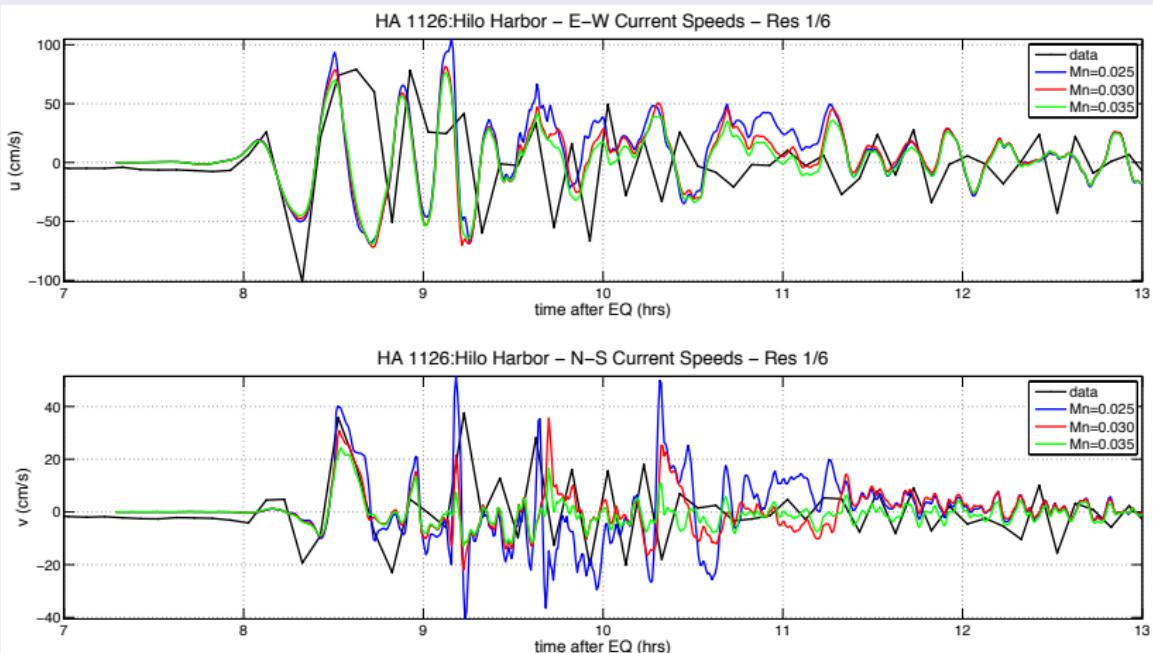
HA1126, Inside Harbour - [lat,lon] = (19.7417,204.9300) - Res 1/6



# Benchmark Problem 2 - Depth-average horizontal velocity data

## 1. Sensitivity to Friction

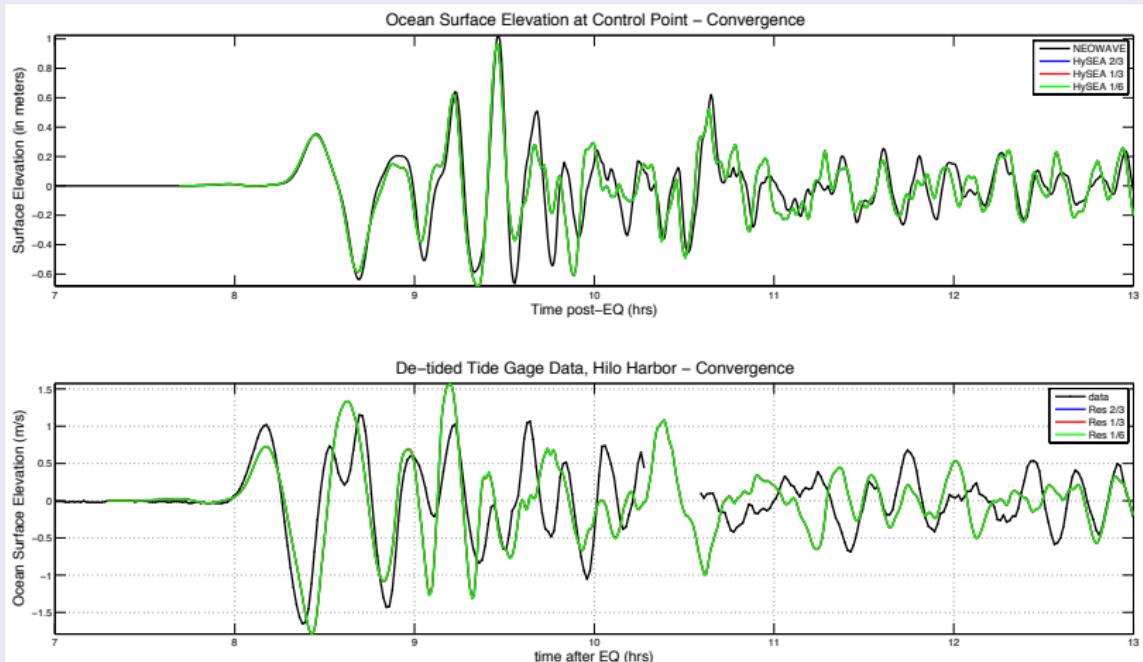
HA1126, Inside Harbour - [lat,lon] = (19.7417,204.9300) - Res 1/6



# Benchmark Problem 2 - Model Resolution

## 2. Convergence: Mesh Refinement

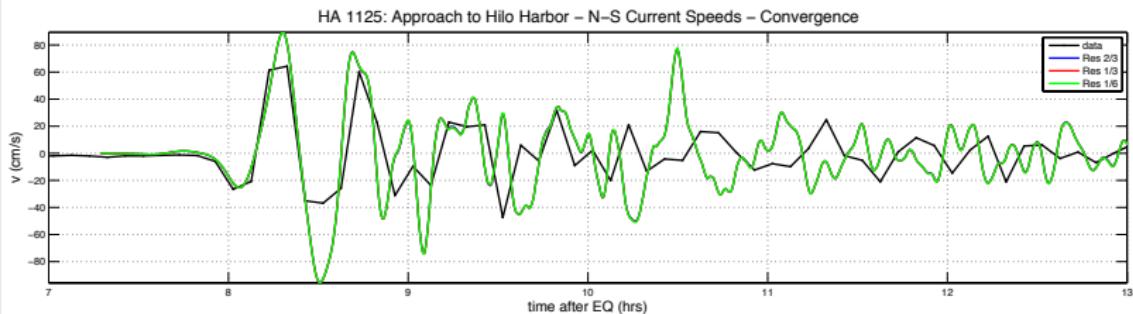
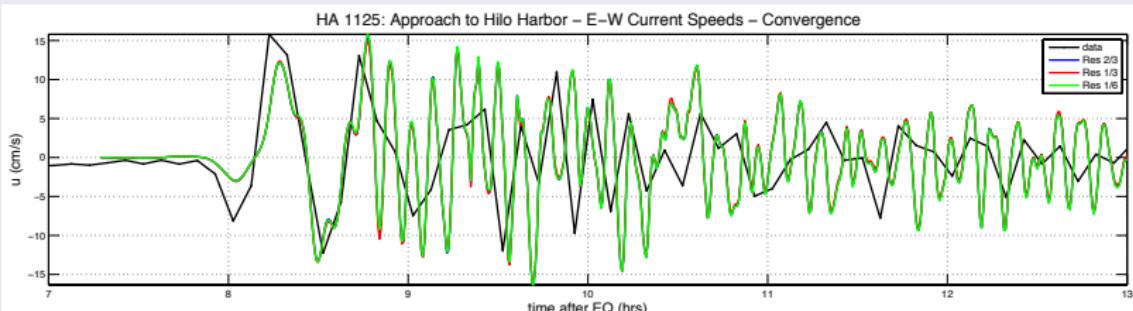
### Sea Surface Elevation - Control Point and Hilo Tide Station



# Benchmark Problem 2 - Model Resolution

## 2. Convergence: Mesh Refinement

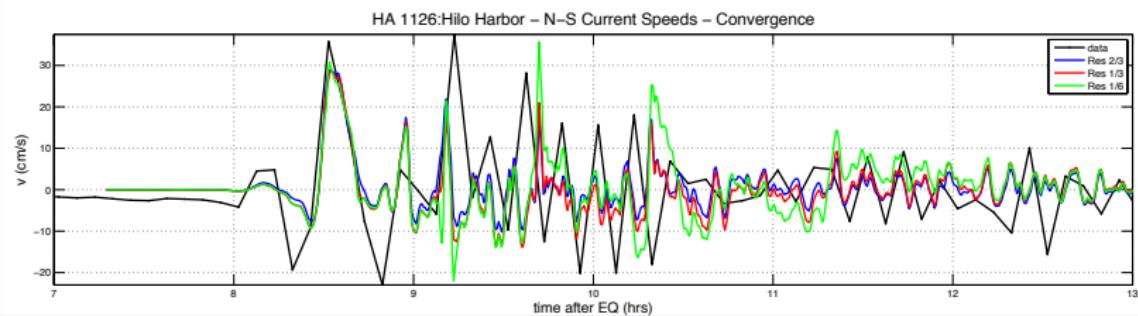
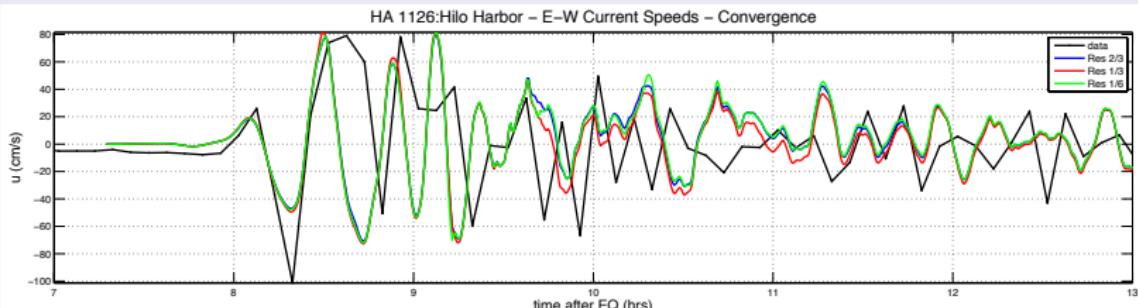
Currents at HA1125, Harbour entrance



# Benchmark Problem 2 - Model Resolution

## 2. Convergence: Mesh Refinement

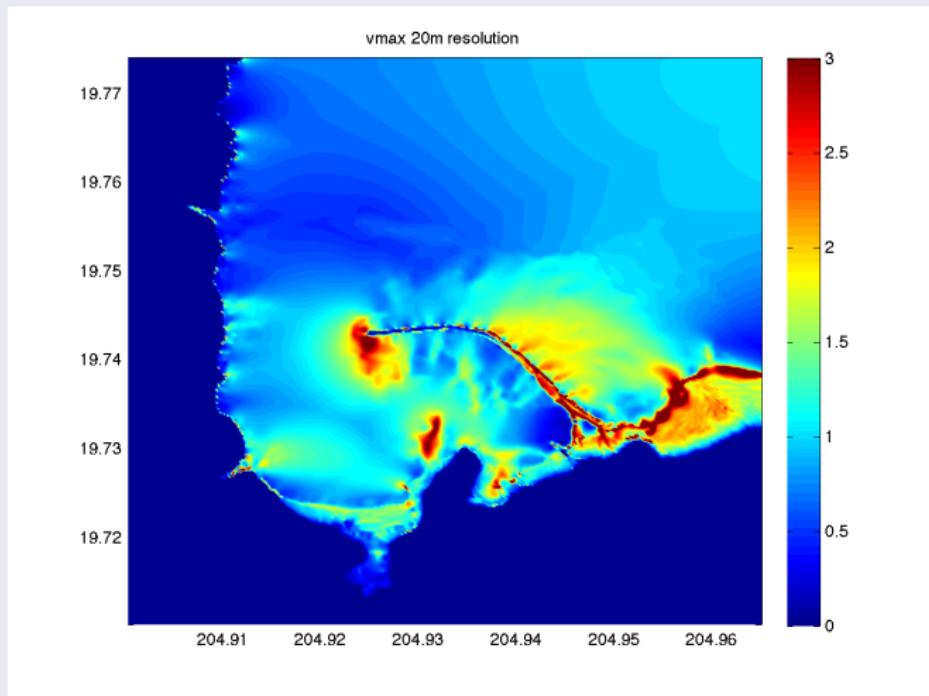
Currents at HA1126, Inside Harbour



# Benchmark Problem 2 - Maximum Speed Maps

## 3. Convergence for Maximum Velocity

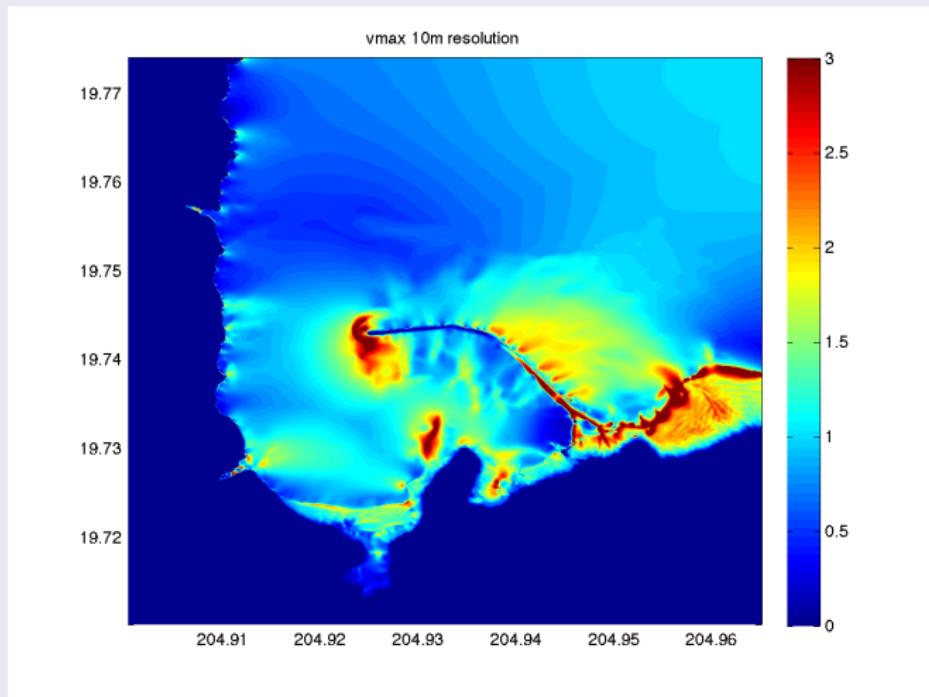
Maximum Speed Map



# Benchmark Problem 2 - Maximum Speed Maps

## 3. Convergence for Maximum Velocity

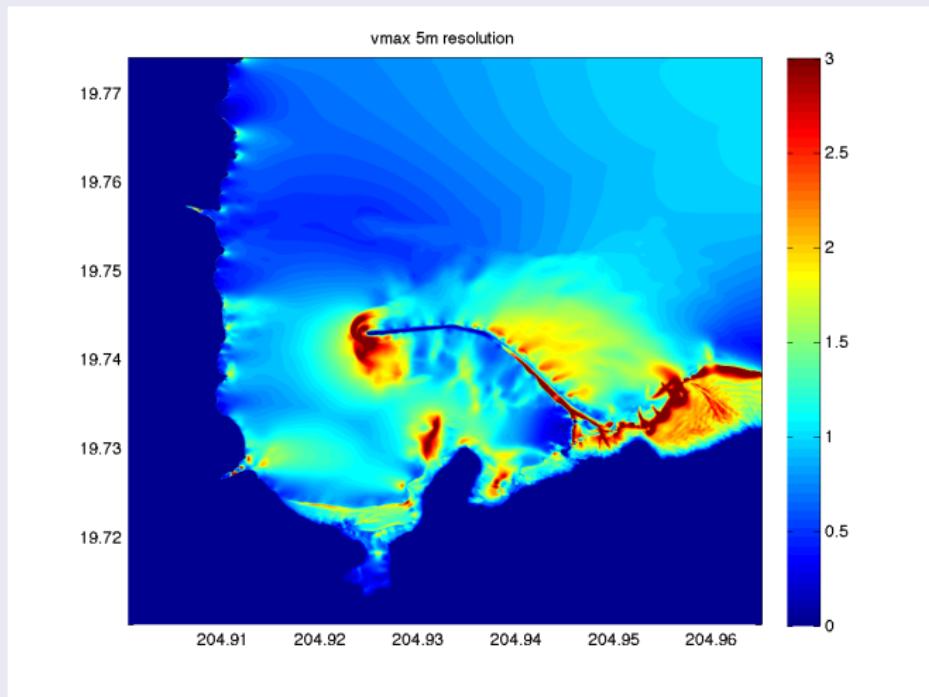
Maximum Speed Map



# Benchmark Problem 2 - Maximum Speed Maps

## 3. Convergence for Maximum Velocity

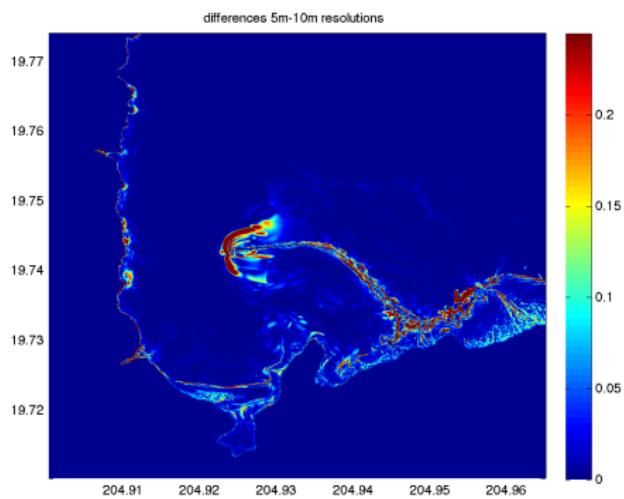
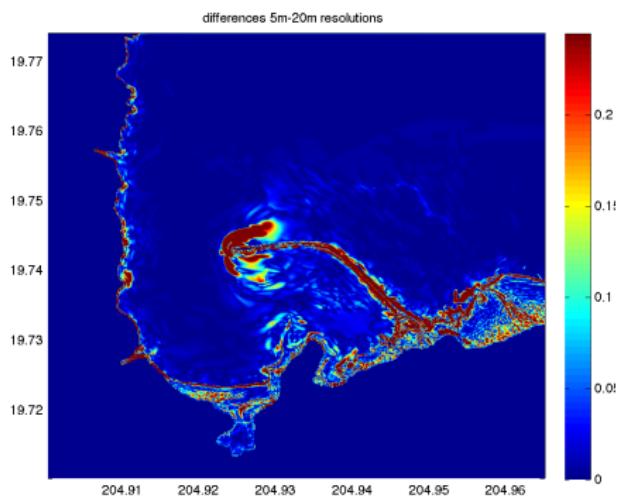
Maximum Speed Map



# Benchmark Problem 2 - Maximum Speed Maps

## 3. Convergence for Maximum Velocity

### Maximum Difference Speed Maps



## Benchmark Problem 2 - Complete scenario

### 2. Complete scenario simulations at different resolutions (encouraged)

- Three level nested mesh decomposition
- Coarse ambient mesh 128/3 arc sec
- Intermediate 8/3 arc sec mesh
- Finer meshes of 2/3, 1/3 and 1/6 arcsec (three resolutions)
- But also varying in resolution coarse and intermediate meshes (256/3 and 16/3)
- Two sources (from NOAA and GeoClaw)

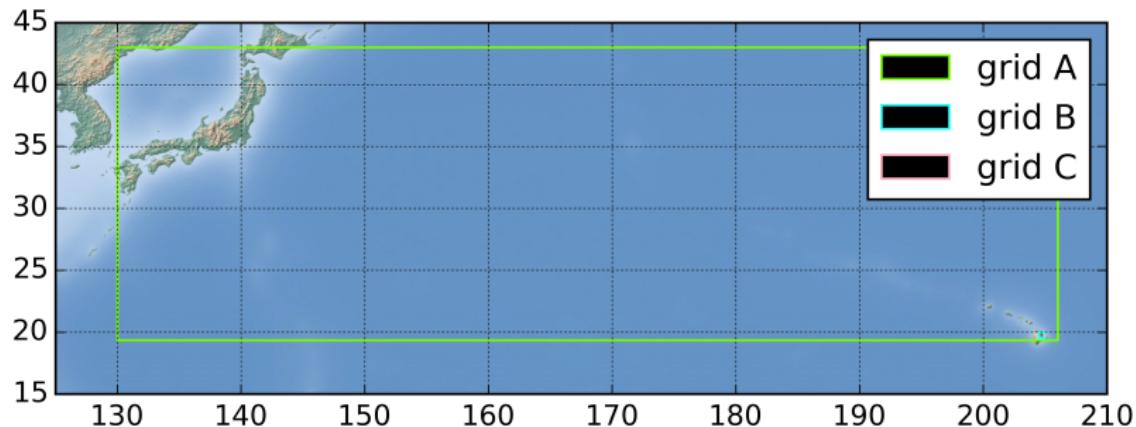
Computational domain [130, 206]×[19.35,43]

Nested Meshes					
Mesh	Resolution	# of cells in lat	# of cells in lon	# of cells	cell size (m)
A	128/3 arc-sec	6,414	1,996	12,802,344	1,280
B	8/3 arc-sec	672	672	451,584	80
C1	2/3 arc-sec	360	352	126,720	20
C2	1/3 arc-sec	720	704	506,880	10
C3	1/6 arc-sec	1,424	1,392	1,982,208	5

## Benchmark Problem 2 - Complete scenario

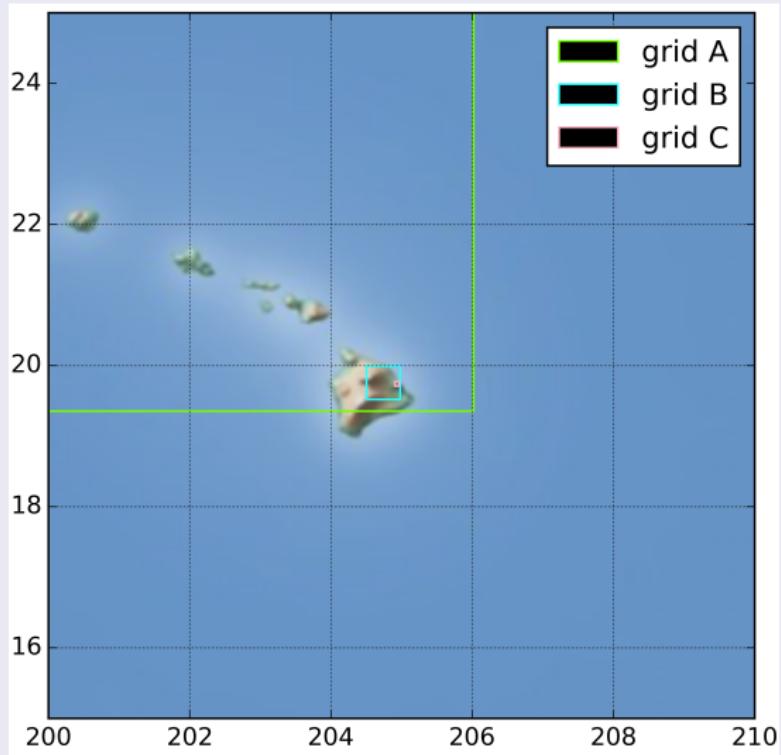
### Nested meshes spatial extension

- Three level nested mesh decomposition
- A :  $[130, 206] \times [19.35, 43]$  ( $128/3$  arc sec)
- B :  $[204.5, 204.97] \times [19.52, 20]$  ( $8/3$  arc sec)
- C :  $[204.9, 204.965] \times [19.711, 19.773]$  ( $2/3$ ,  $1/3$  and  $1/6$  arcsec)



## Benchmark Problem 2 - Complete scenario

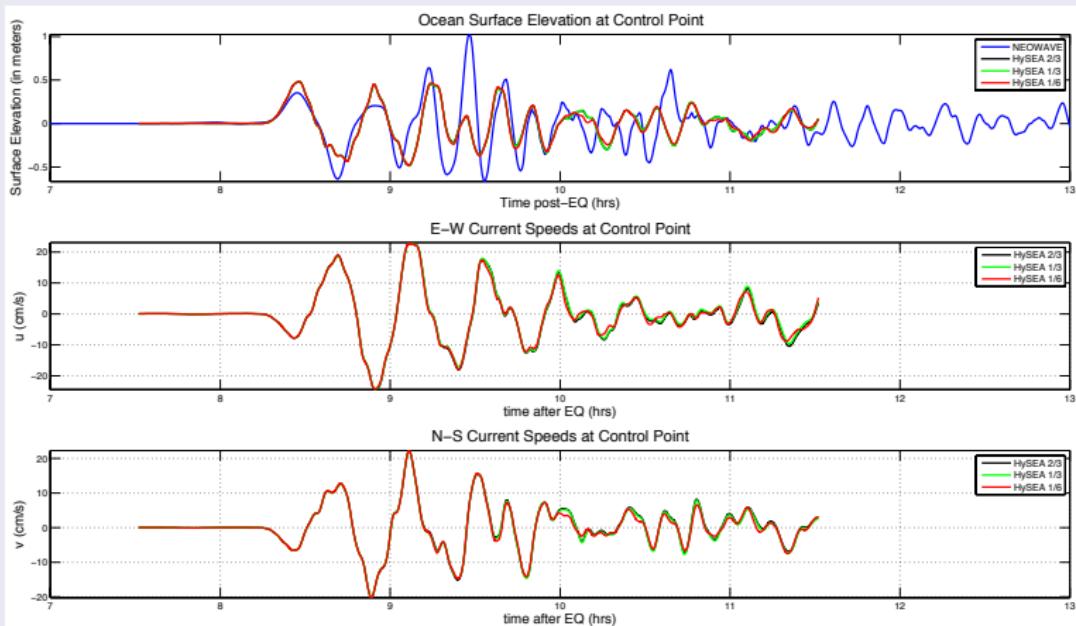
Nested meshes spatial extension



# Benchmark Problem 2 - Complete scenario - Time series at control point

## 1. Sensitivity to mesh refinement - Inner Mesh

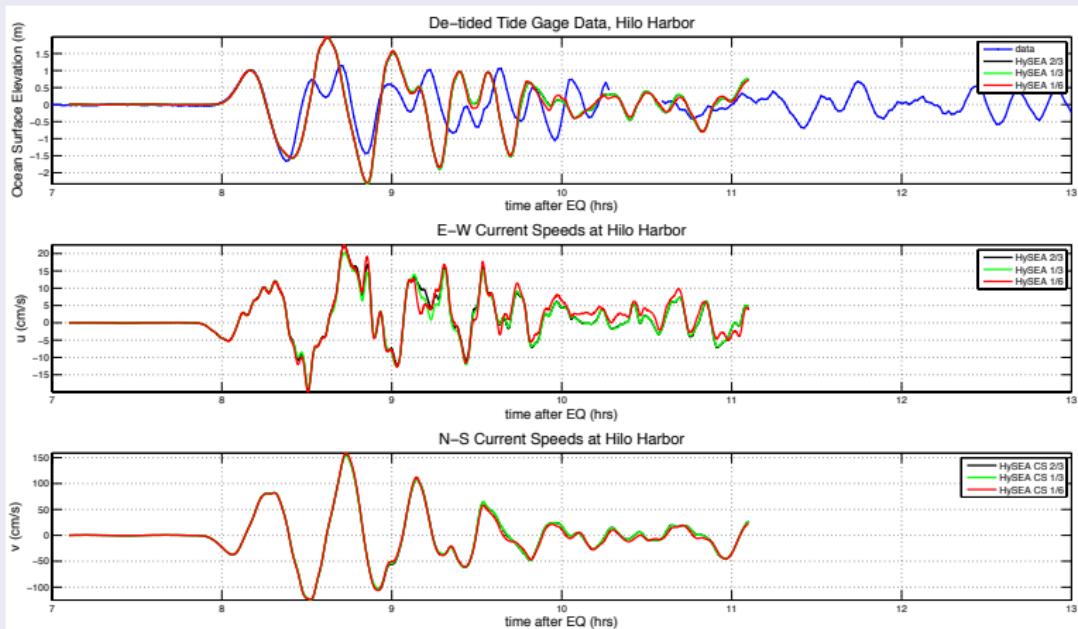
Control Point - [lat,lon] = (19.7576,204.93)



# Benchmark Pb 2 - Complete scenario - Time series at the tidal station

## 1. Sensitivity to mesh refinement - Inner Mesh

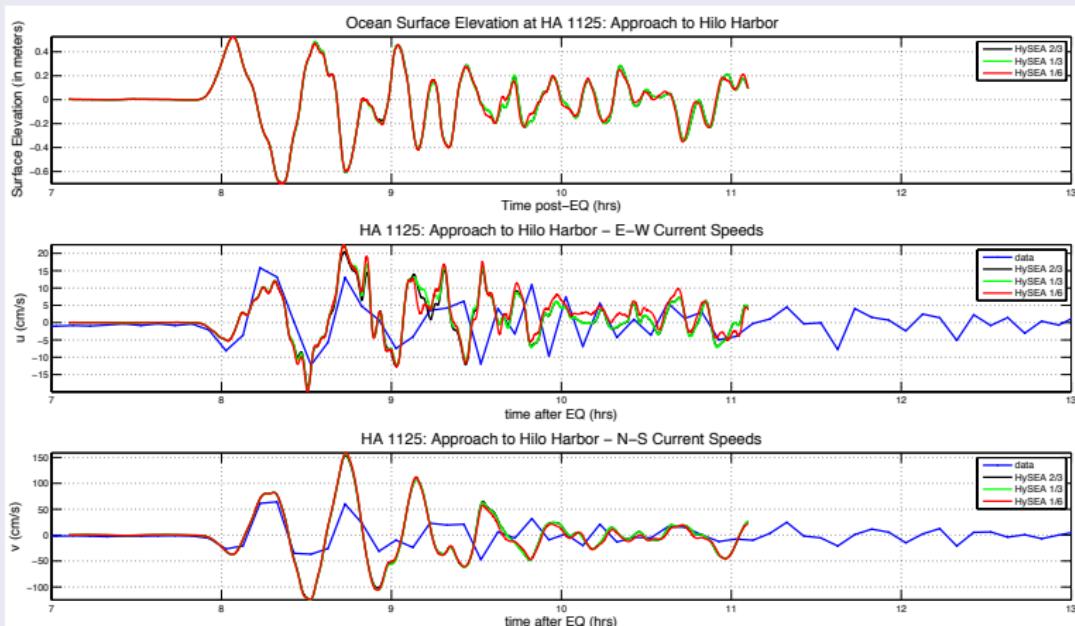
Hilo Tide Station - [lat,lon] = (19.7308,204.9447)



# Benchmark Problem 2 - Complete scenario - Time series at HA1125

## 1. Sensitivity to mesh refinement - Inner Mesh

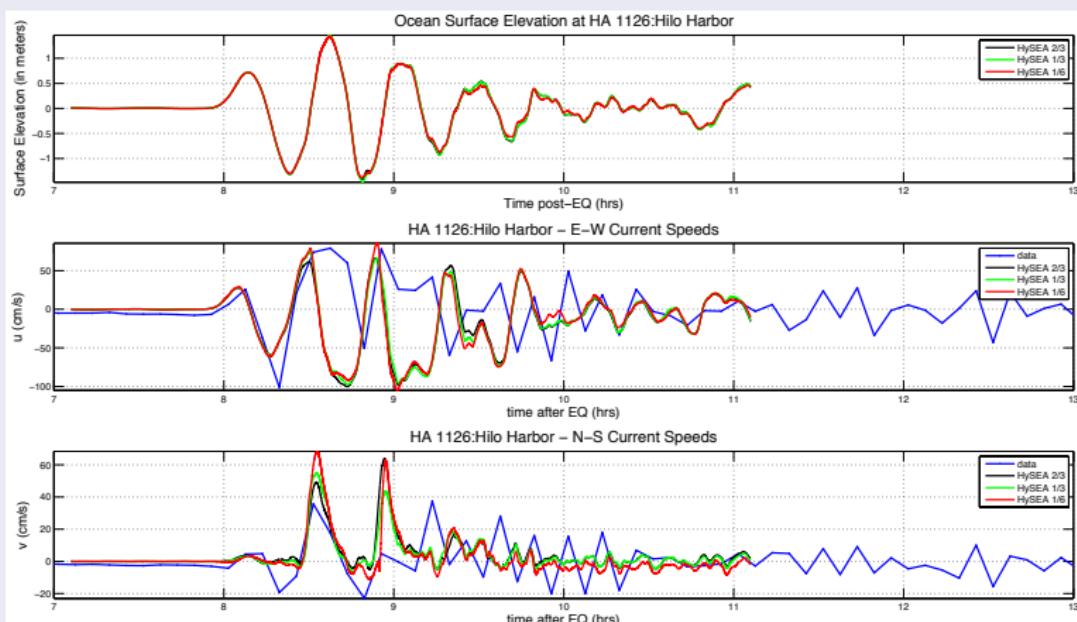
HA1125, Harbour entrance - [lat,lon] = (19.7452,204.9180)



# Benchmark Problem 2 - Complete scenario -Time series at HA1126

## 1. Sensitivity to mesh refinement - Inner Mesh

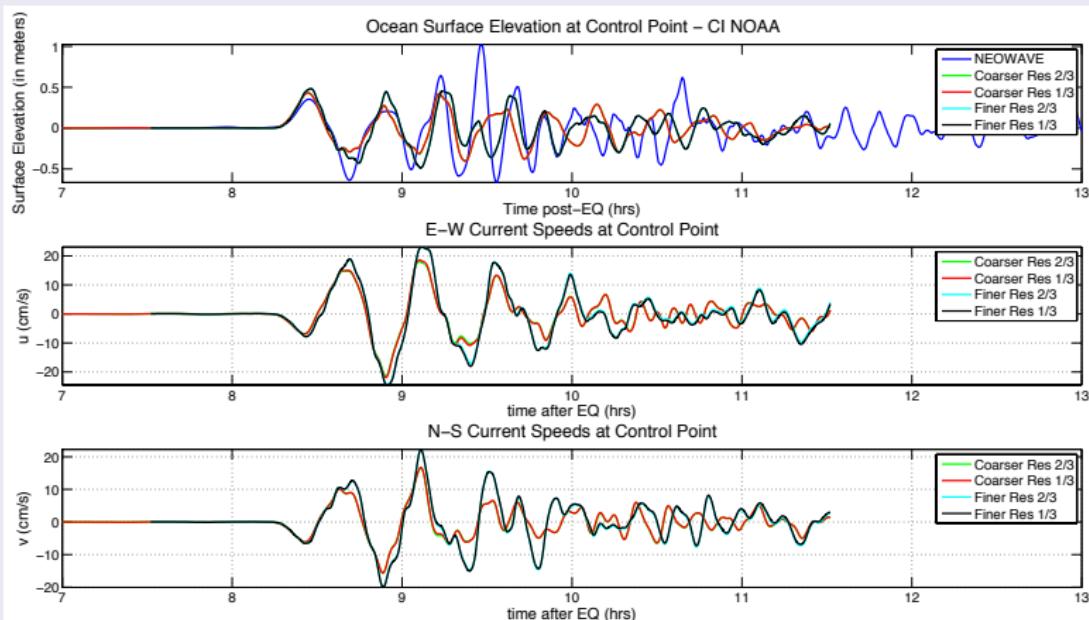
HA1126, Inside Harbour - [lat,lon] = (19.7417,204.9300)



# Benchmark Problem 2 - Complete scenario - Time series at control point

## 2. Sensitivity to mesh refinement - Ambient and Intermediate Meshes

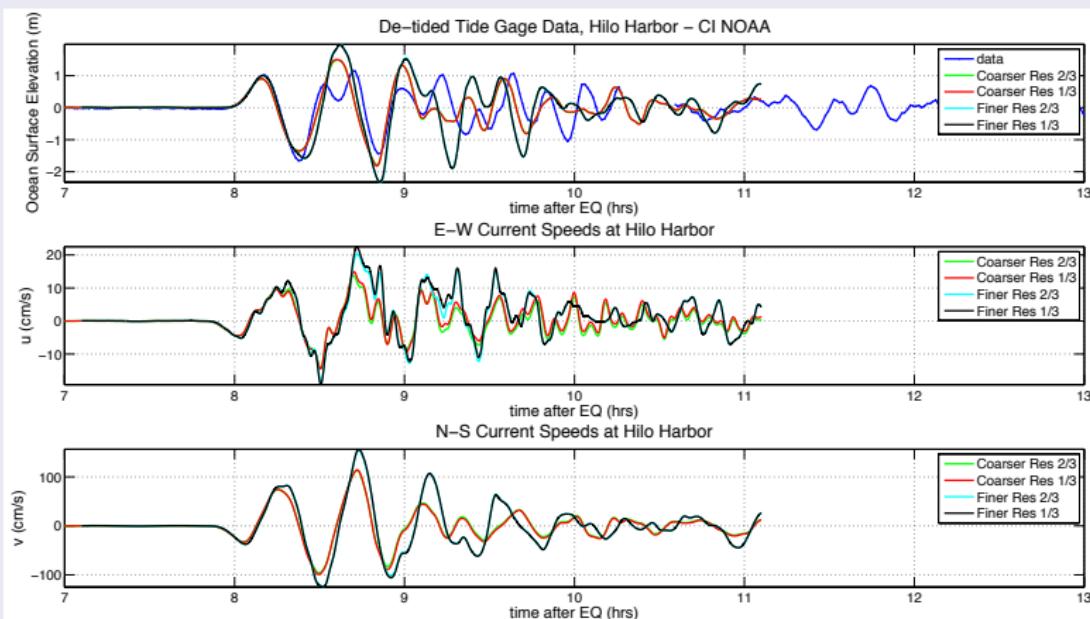
Control Point - [lat,lon] = (19.7576,204.93)



# Benchmark Pb 2 - Complete scenario - Time series at the tidal station

## 2. Sensitivity to mesh refinement - Ambient and Intermediate Meshes

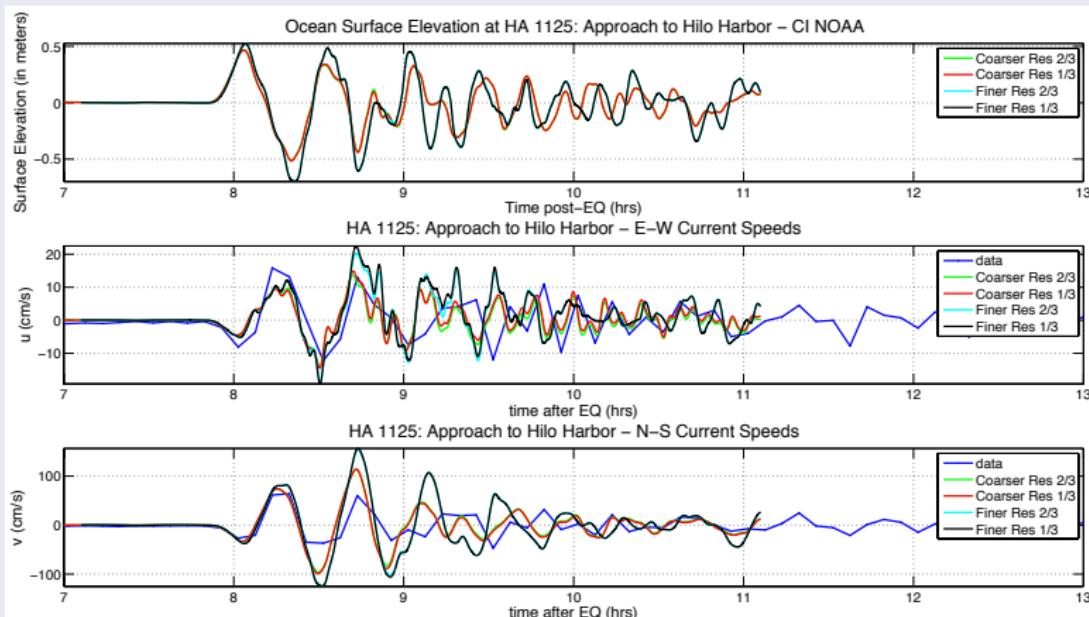
Hilo Tide Station - [lat,lon] = (19.7308,204.9447)



# Benchmark Problem 2 - Complete scenario -Time series at HA1125

## 2. Sensitivity to mesh refinement - Ambient and Intermediate Meshes

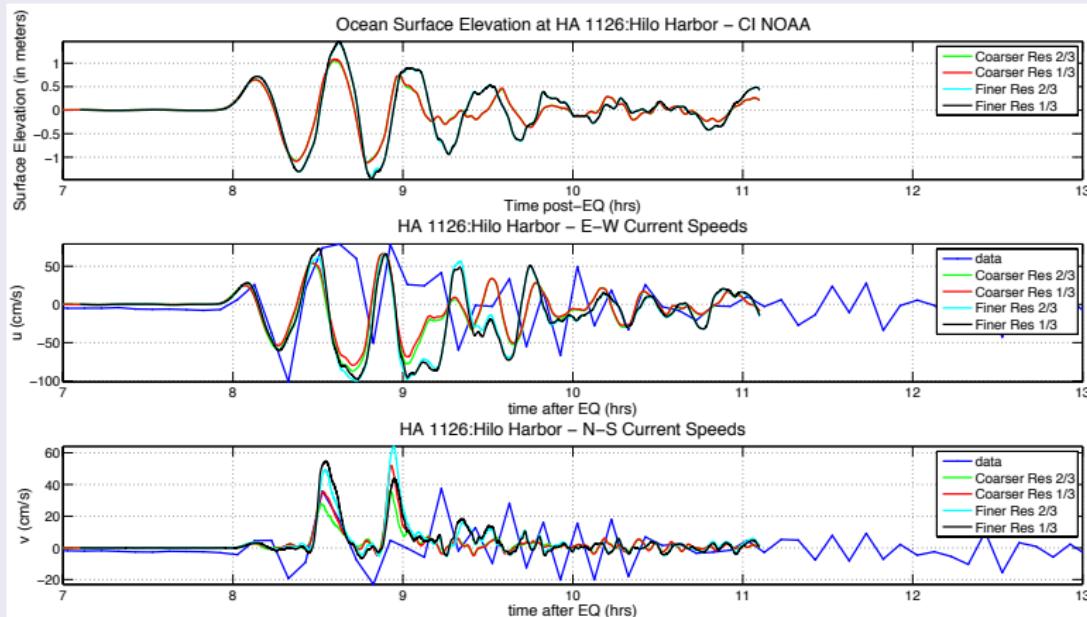
HA1125, Harbour entrance - [lat,lon] = (19.7452,204.9180)



# Benchmark Problem 2 - Complete scenario -Time series at HA1126

## 2. Sensitivity to mesh refinement - Ambient and Intermediate Meshes

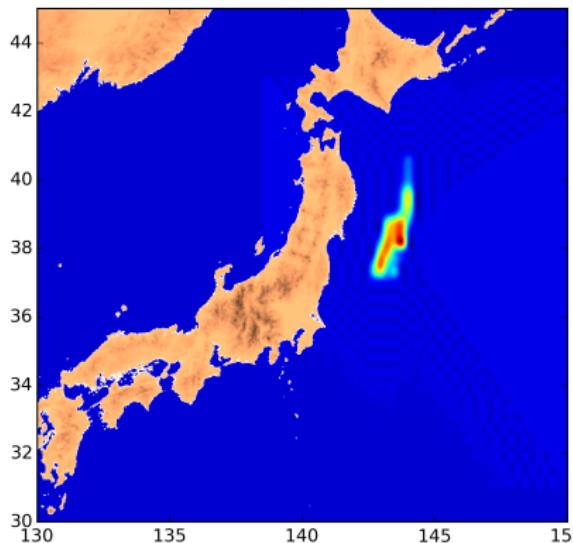
HA1126, Inside Harbour - [lat,lon] = (19.7417,204.9300)



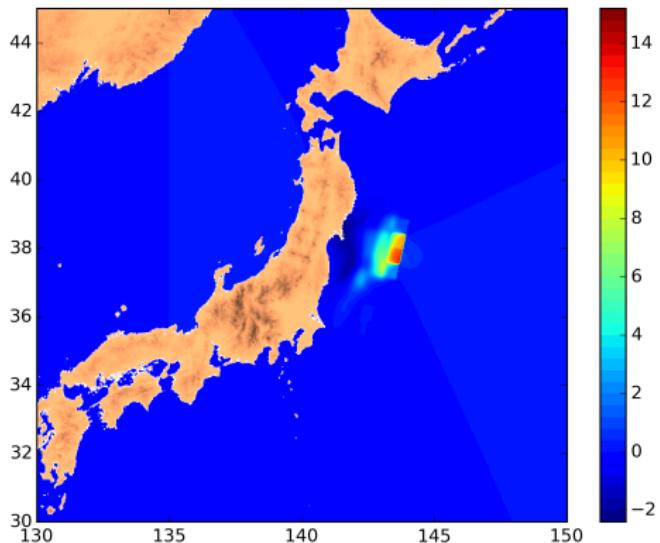
# Benchmark Problem 2 - Complete scenario - Initial Conditions

## 3. Two Sources as Initial Condition (NOAA and GeoClaw)

**NOAA**



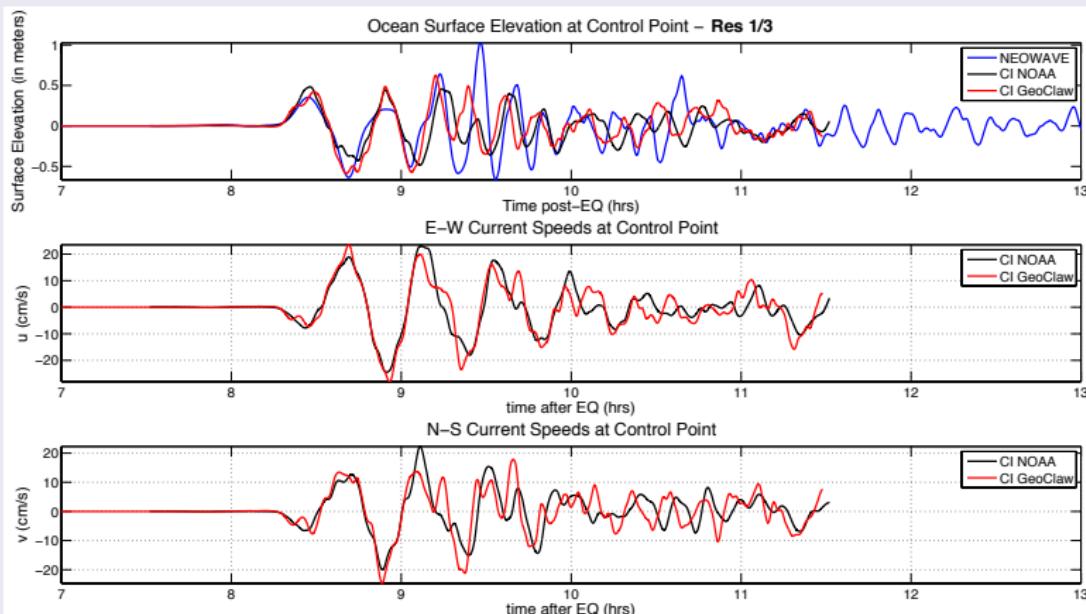
**GeoClaw**



# Benchmark Problem 2 - Complete scenario - Time series at control

## 3. Two Sources as Initial Condition (NOAA and GeoClaw)

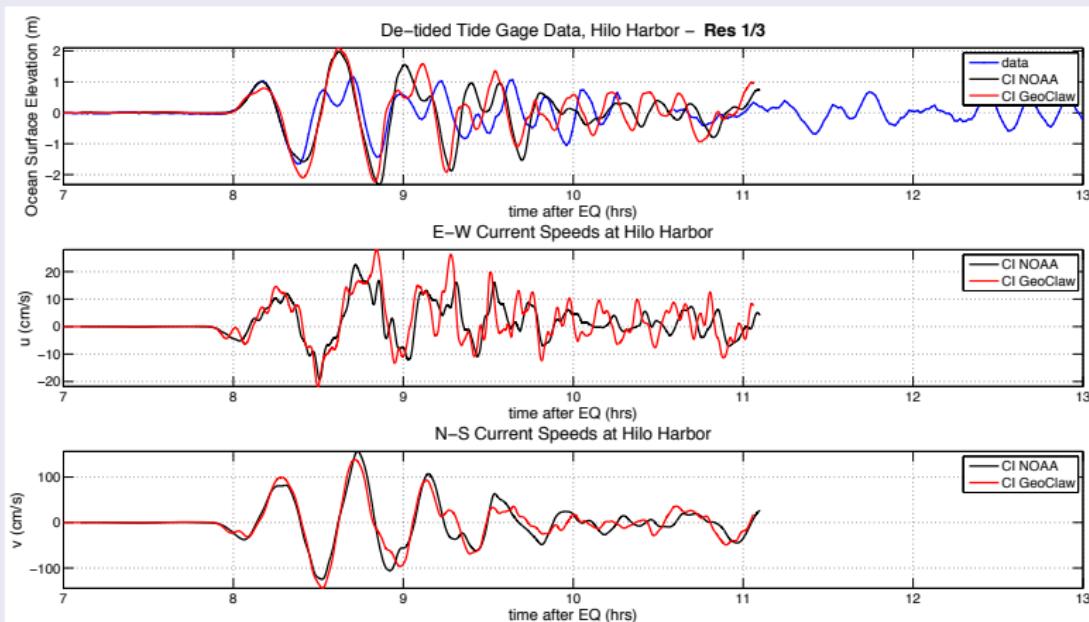
Control Point - [lat,lon] = (19.7576,204.93)



# Benchmark Pb 2 - Complete scenario - Time series at the tidal station

## 3. Two Sources as Initial Condition (NOAA and GeoClaw)

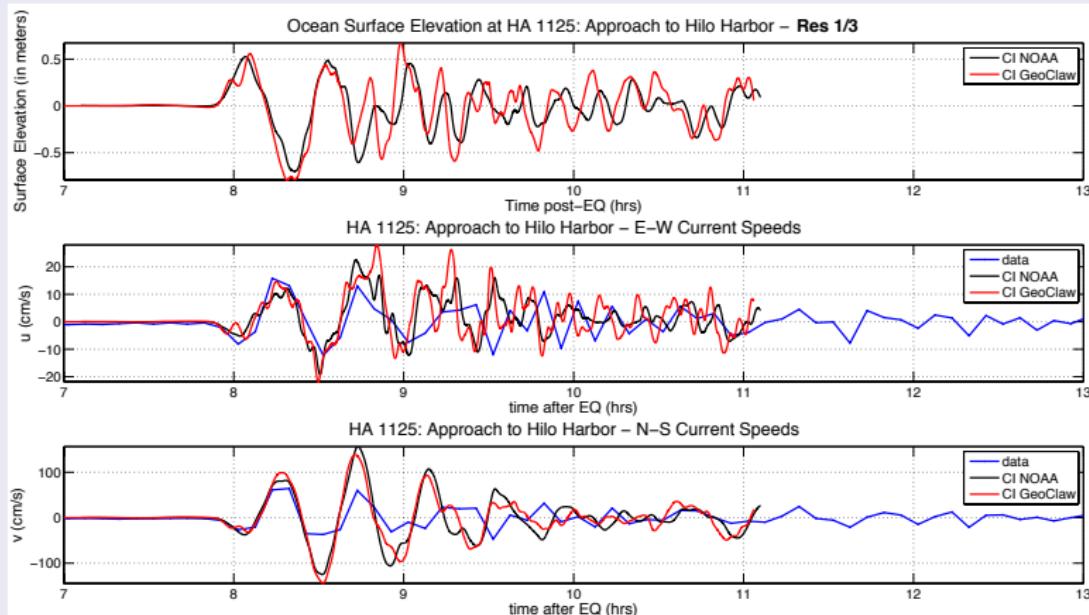
Hilo Tide Station - [lat,lon] = (19.7308,204.9447)



# Benchmark Problem 2 - Complete scenario - Time series at HA1125

## 3. Two Sources as Initial Condition (NOAA and GeoClaw)

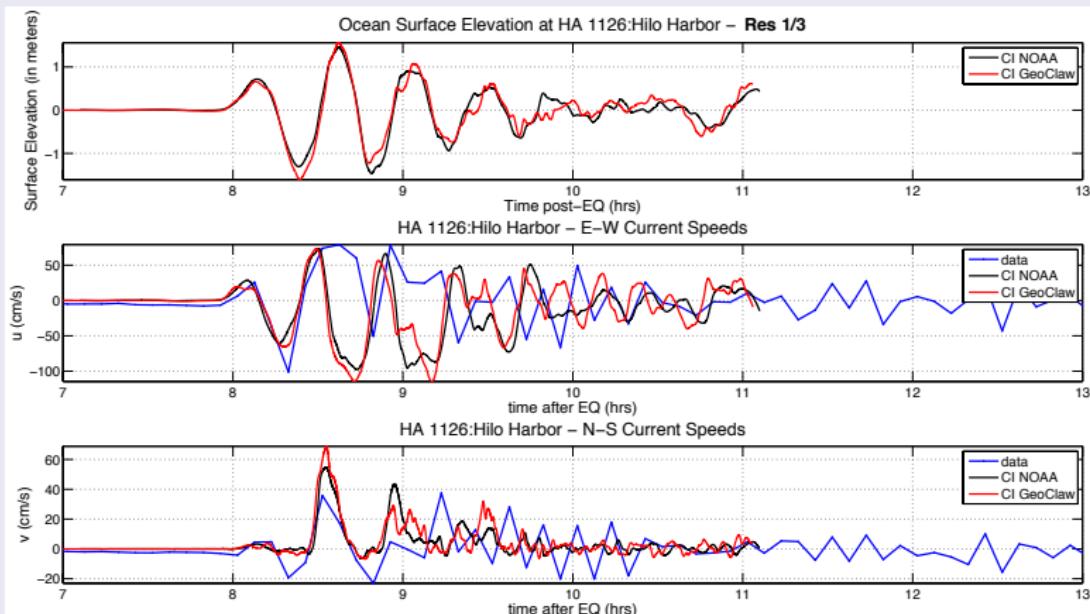
HA1125, Harbour entrance - [lat,lon] = (19.7452,204.9180)



# Benchmark Problem 2 - Complete scenario - Time series at HA1126

## 3. Two Sources as Initial Condition (NOAA and GeoClaw)

HA1126, Inside Harbour - [lat,lon] = (19.7417,204.9300)

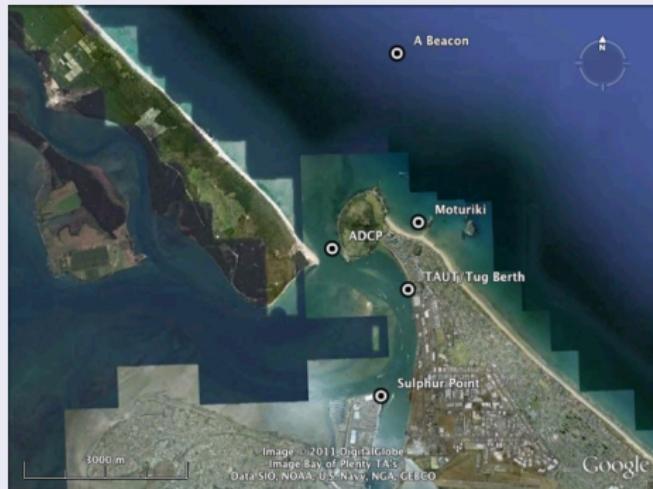


# Benchmark Problem 3 - Tauranga Harbour

## Description and Aim

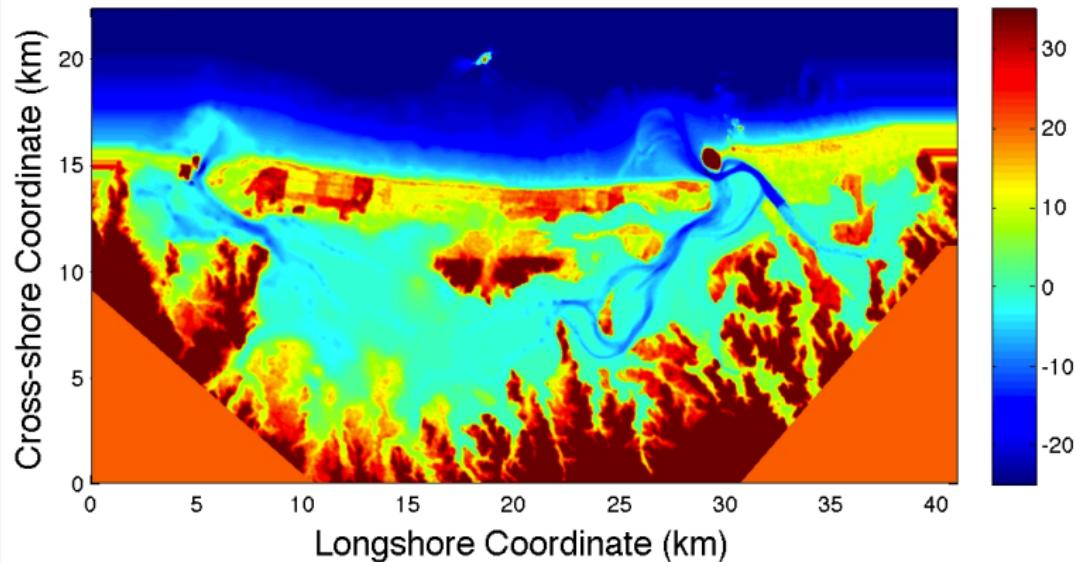
- **Field dataset** - Japan 2011 in Tauranga Harbour (New Zealand)
- Aim: **Attempt to include effects of tides**

## Observed Data



# Benchmark Problem 3 - Tauranga Harbour

## Setup - Bathymetry



# Benchmark Problem 3 - Tauranga Harbour

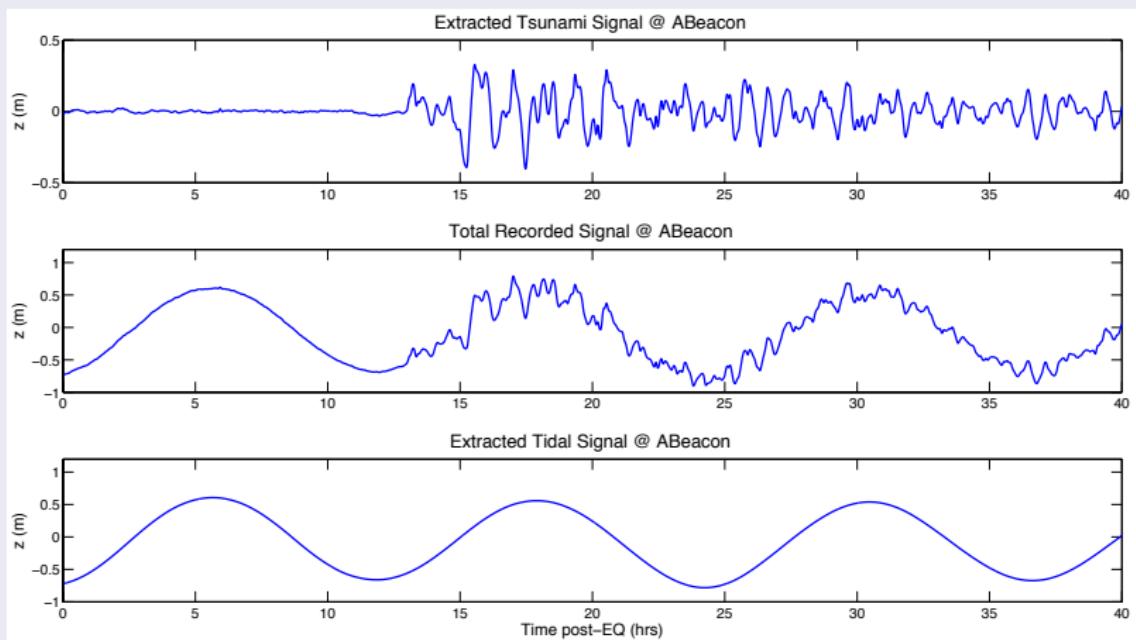
## Setup

- Domain:  $[0, 40000] \times [0, 20000]$  in meters (rotated) -  $40 \text{ km} \times 20 \text{ km}$
- Data Resolution: 10 m
- Numerical resolution: 20 m ( $a \times b$ )

# Benchmark Problem 3 - Tauranga Harbour

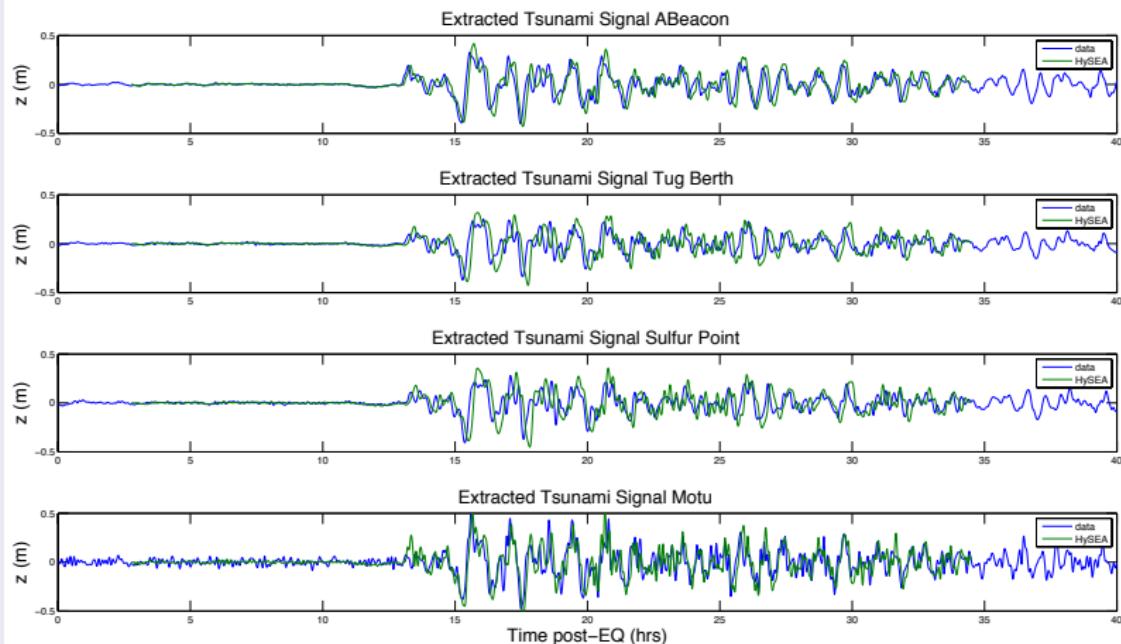
## Setup - Boundary Condition

- Use most offshore measured free surface elevation data (ABeacon tide gage)



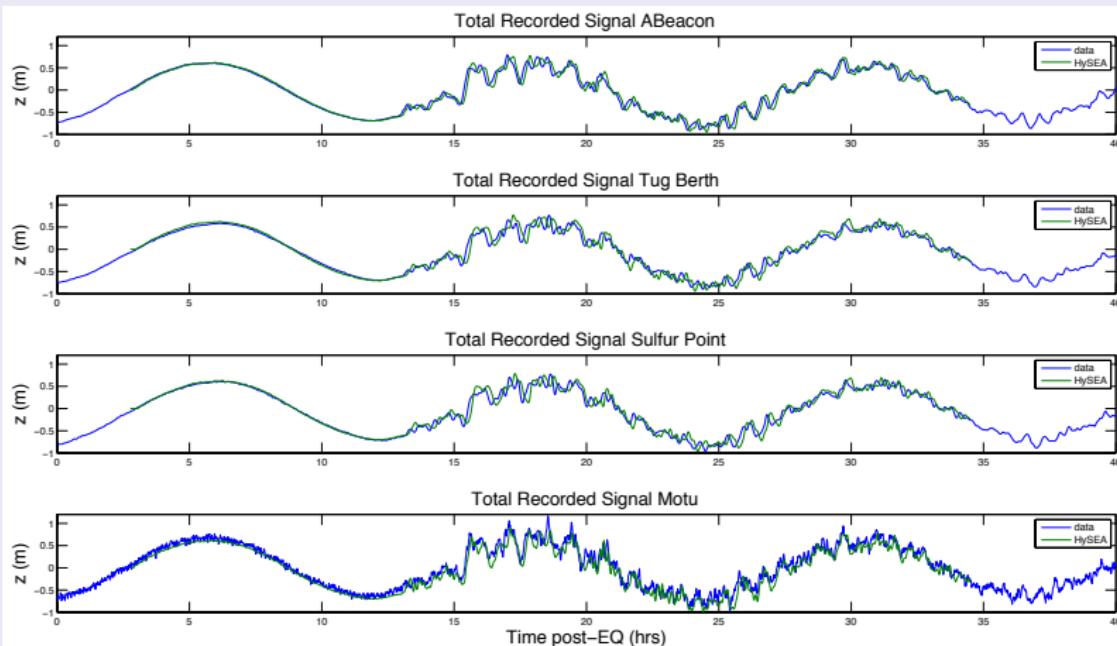
# Benchmark Problem 3 - Free surface elevation at the 4 tidal stations

## Tsunami-Only signal



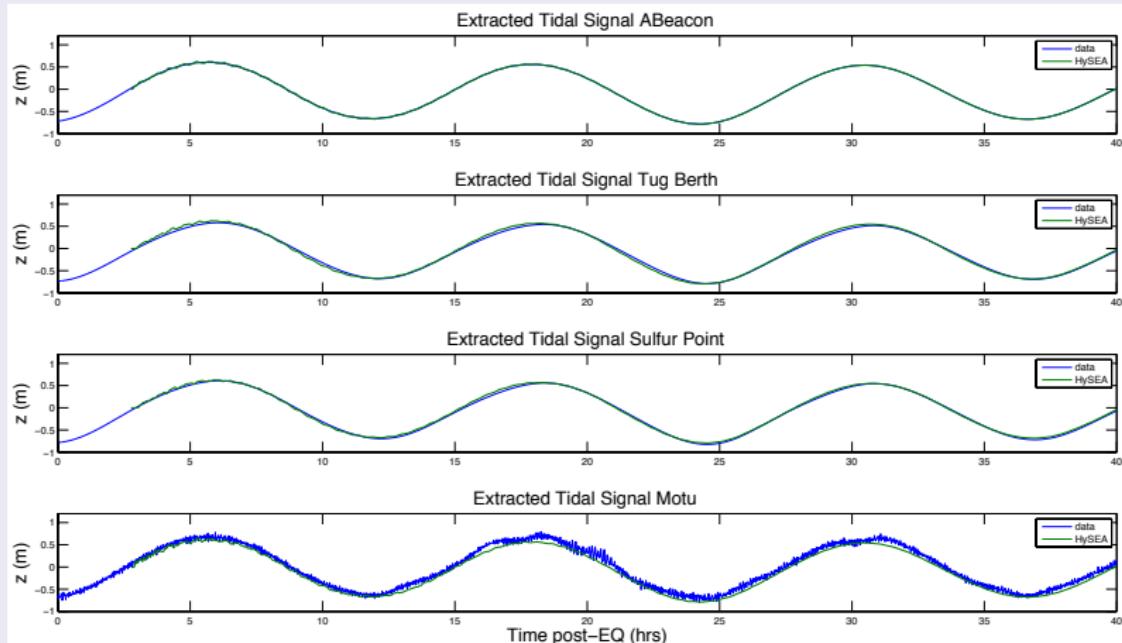
# Benchmark Problem 3 - Free surface elevation at the 4 tidal stations

## Tsunami + Tide signal



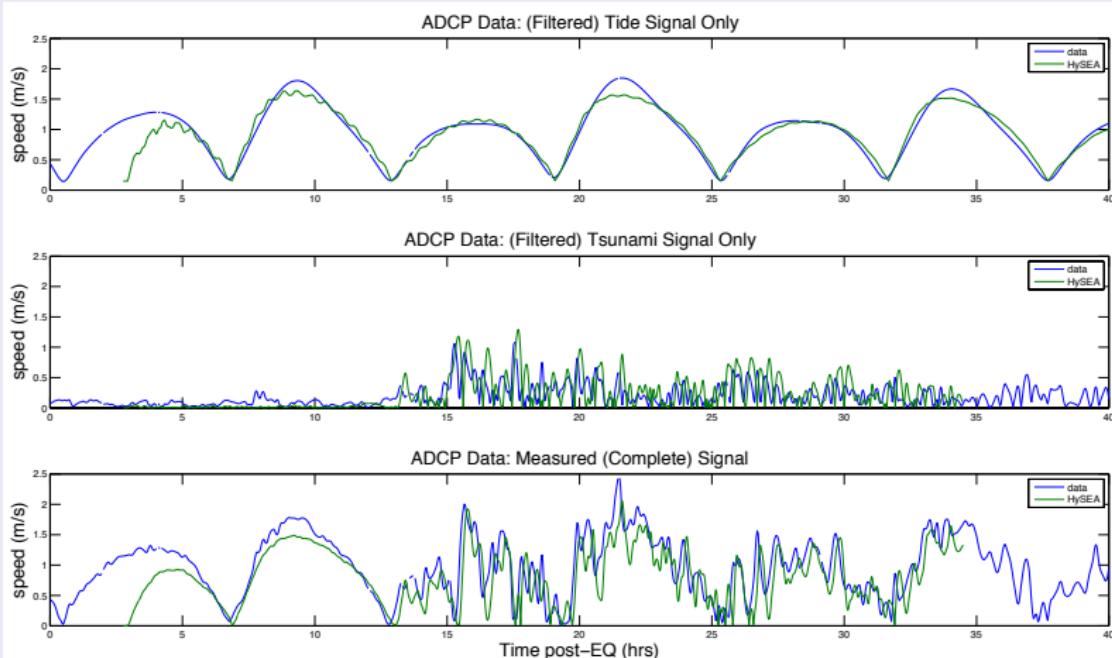
# Benchmark Problem 3 - Free surface elevation at the 4 tidal stations

## Tide-Only signal



# Benchmark Problem 3 - Depth-Average Horizontal Velocity data

ADCP: [lat,lon] = (-37.6307,176.18377) - [x,y] = (29250,14660) (rotated)

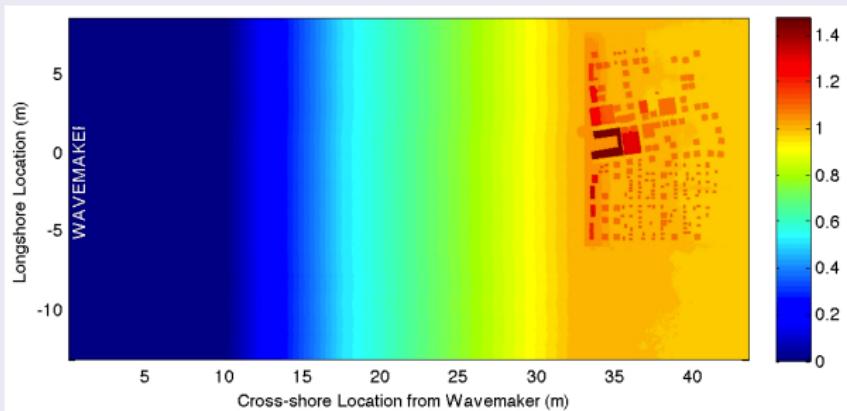


# Benchmark Problem 4 - Seaside (Oregon)

## Description

- Single long-period wave
- Piecewise linear slope and small scale model of Seaside (Oregon)
- Free surface information
- Velocity information

## Setup - Bathymetry

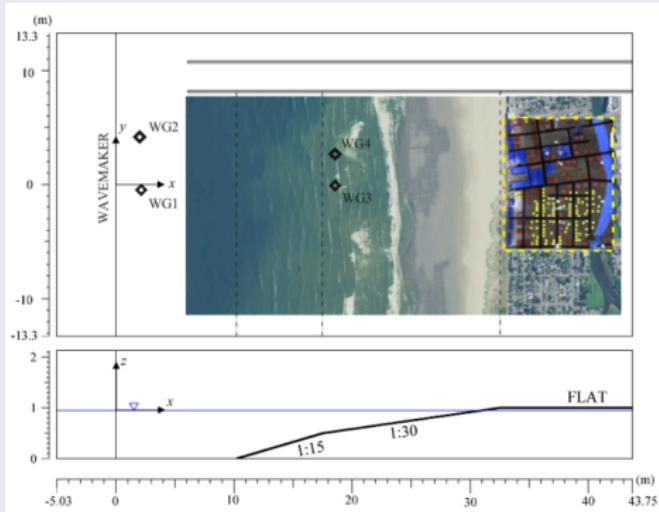


# Benchmark Problem 4 - Seaside (Oregon)

## Setup

- Domain:  $[0.012, 43.633] \times [-13.261, 8.549]$  in meters ( $43.621 \times 21.81$  meters)
- Data Resolution: 0.01 m
- Mesh:  $4363 \times 2182$

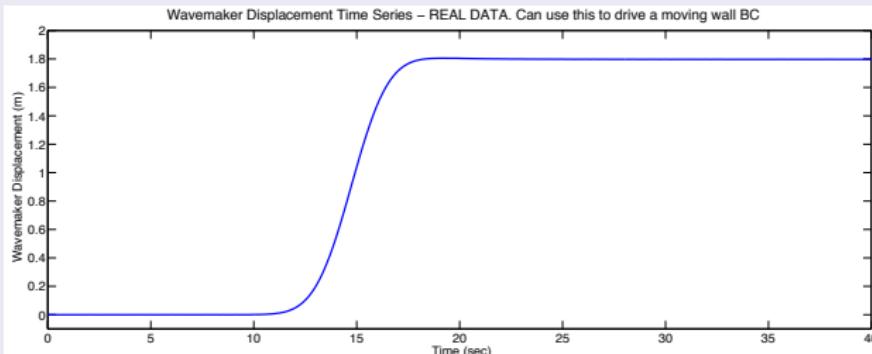
## Physical Model



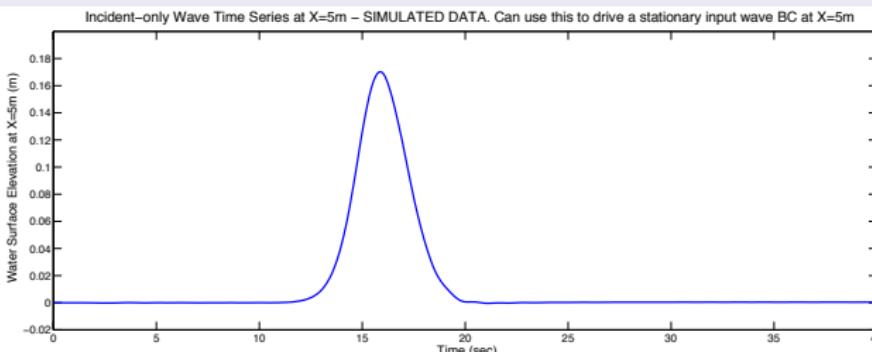
# Benchmark Problem 4 - Seaside (Oregon)

## Setup - Boundary Condition

- Wavemaker

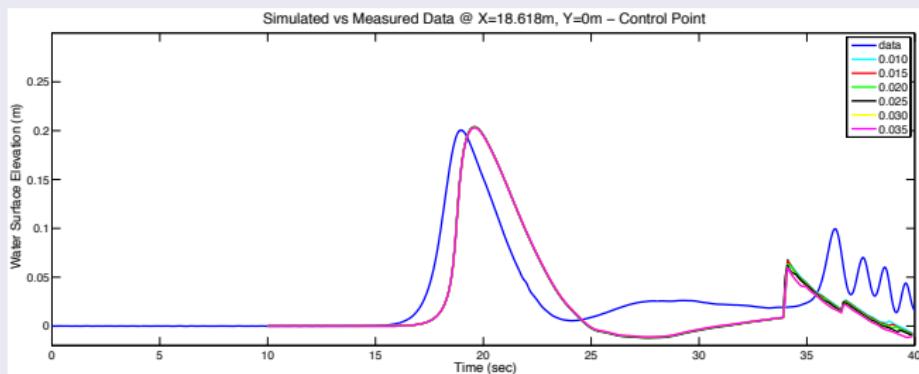


- Incident wave time series at  $x=5\text{ m}$



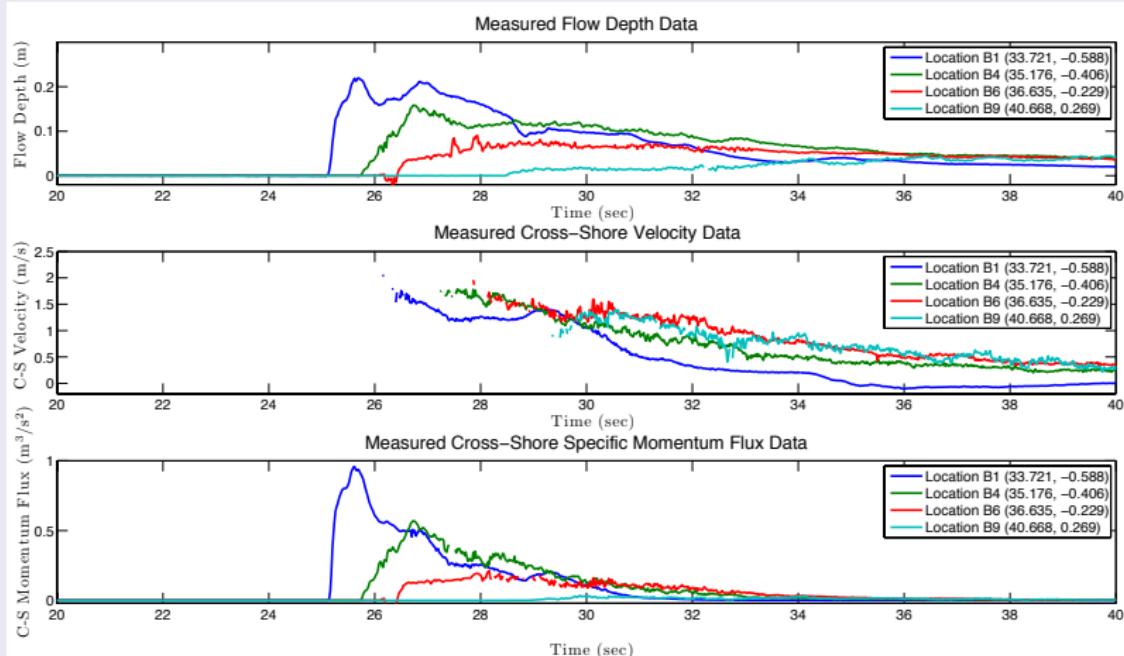
# Benchmark Problem 4 - Seaside (Oregon)

## Water surface elevation at WG3



# Benchmark Problem 4 - Seaside (Oregon)

Measured Data at B1, B4, B6, B9 (Flow Depth - Velocity - Specific Momentum Flux)

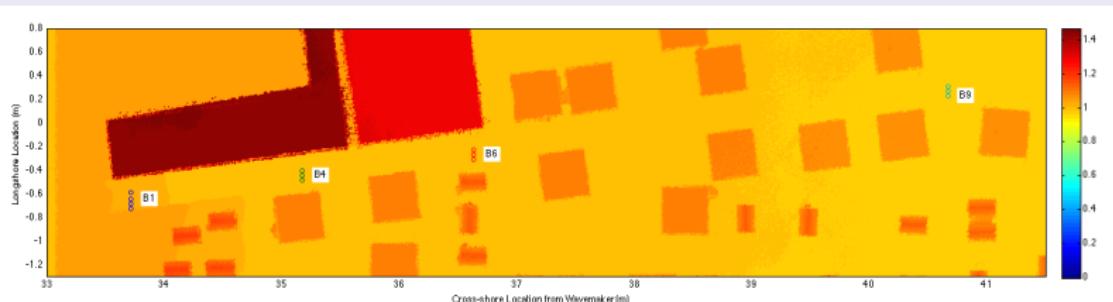


# Benchmark Problem 4 - Seaside (Oregon)

## What we have done

- Numerical Resolution: 1 and 2 cm
- Numerical scheme: Order 1, 2 and WAF (Order 2 presented)
- Varying friction (from 0.01 to 0.035)
- Spatial variability (4 cm distance)

## Spatial Variability

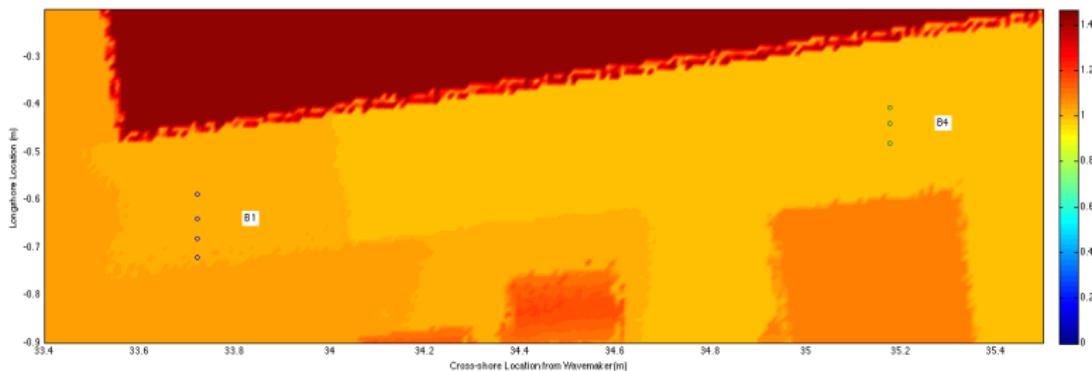


# Benchmark Problem 4 - Seaside (Oregon)

## What we have done

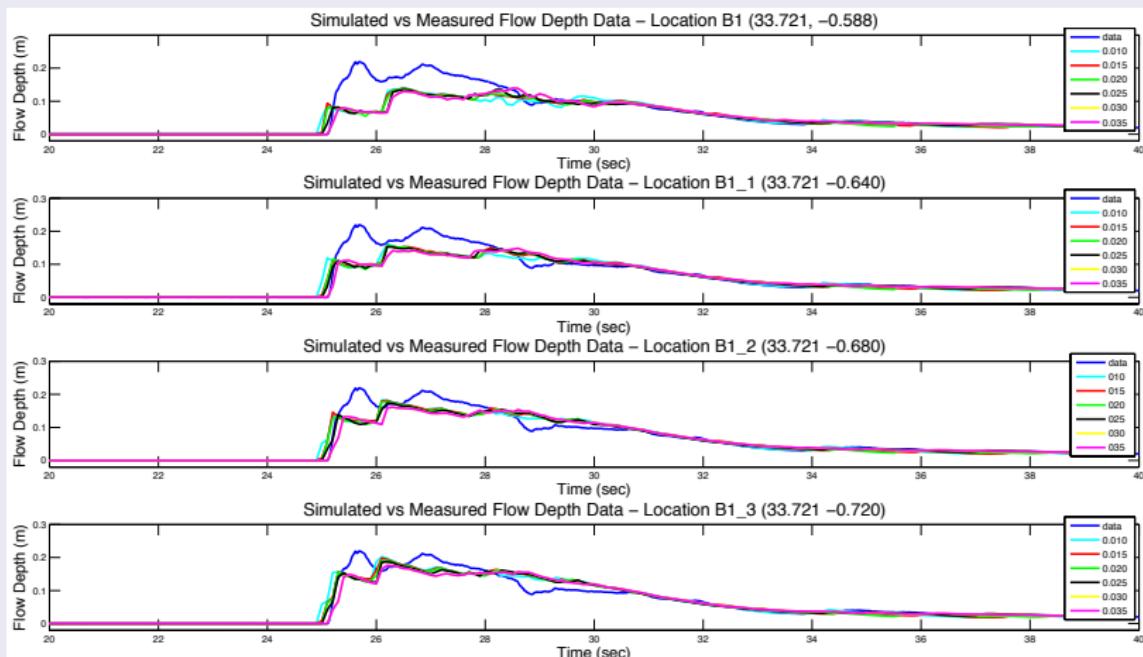
- Numerical Resolution: 1 and 2 cm
- Numerical scheme: Order 1, 2 and WAF (Order 2 presented)
- Varying friction (from 0.01 to 0.035)
- Spatial variability (4 cm distance)

## Spatial Variability



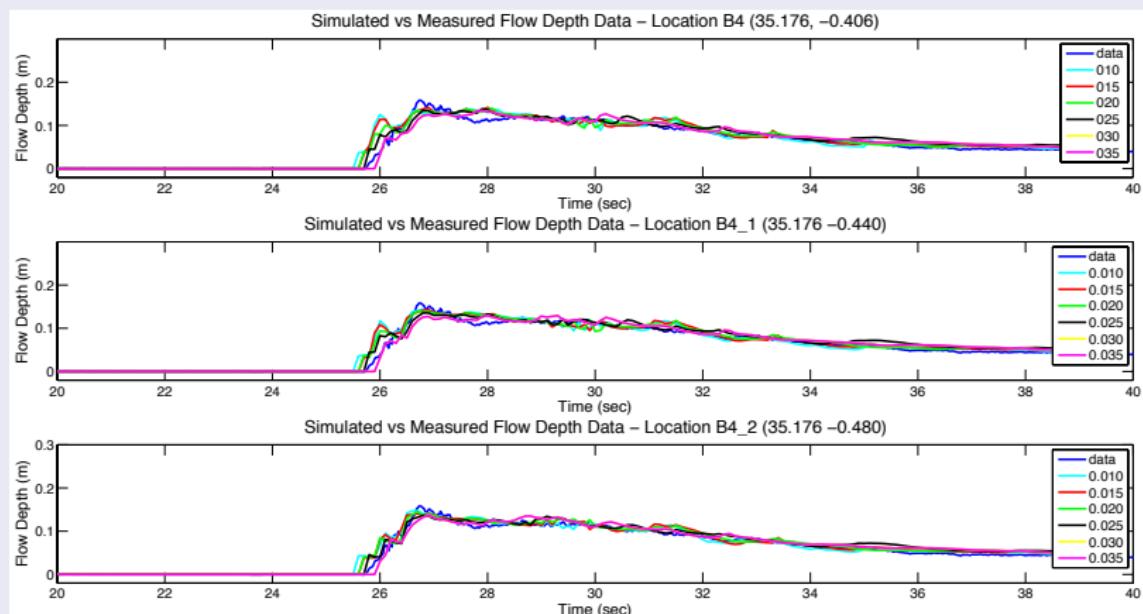
# Benchmark Problem 4 - Seaside (Oregon)

## Flow Depth Spatial Variability for all the “B1” points



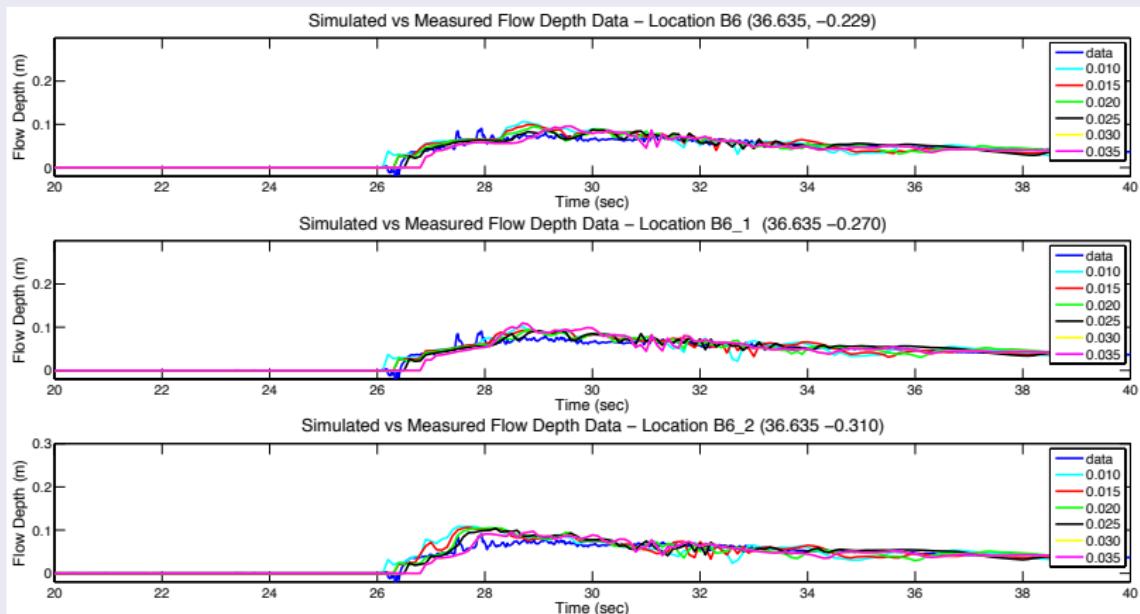
# Benchmark Problem 4 - Seaside (Oregon)

## Flow Depth Spatial Variability for all the “B4” points



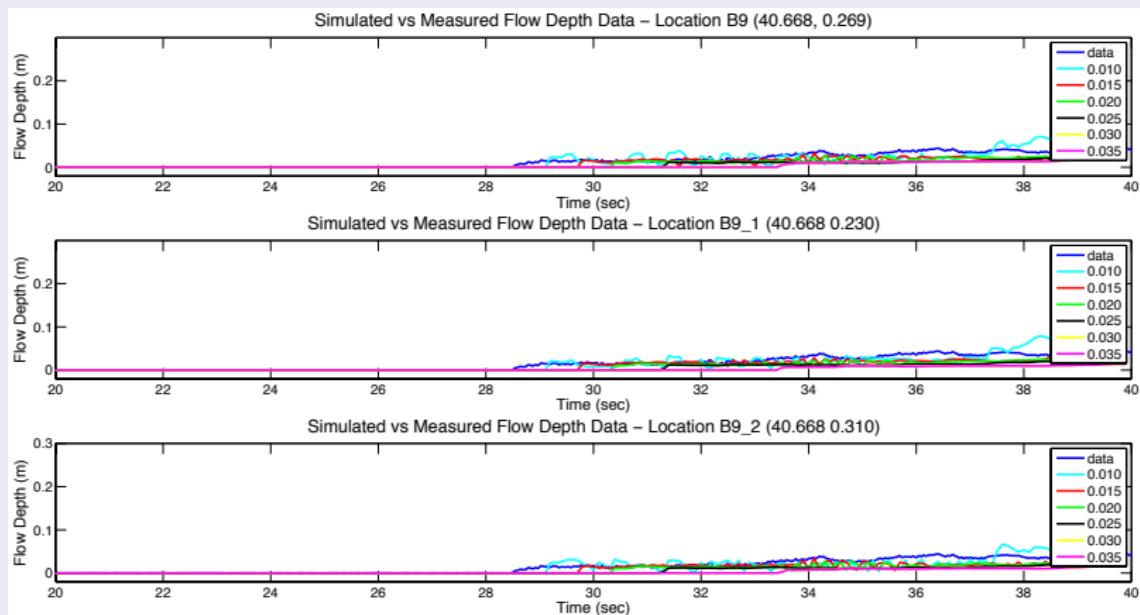
# Benchmark Problem 4 - Seaside (Oregon)

## Flow Depth Spatial Variability for all the “B6” points



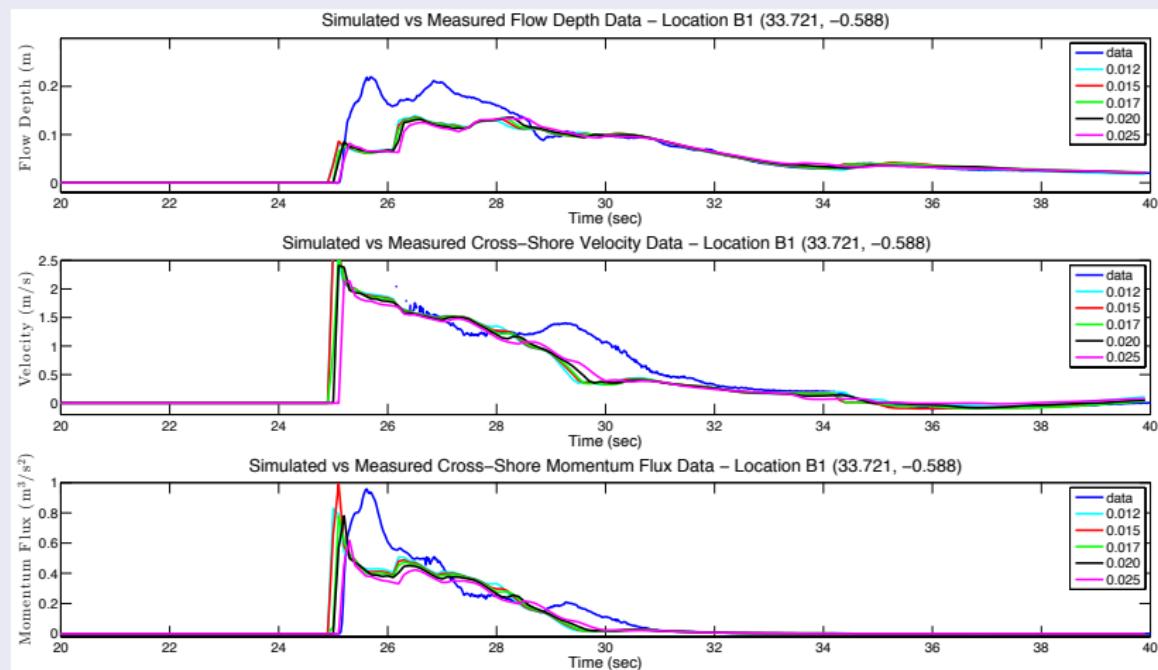
# Benchmark Problem 4 - Seaside (Oregon)

## Flow Depth Spatial Variability for all the “B9” points



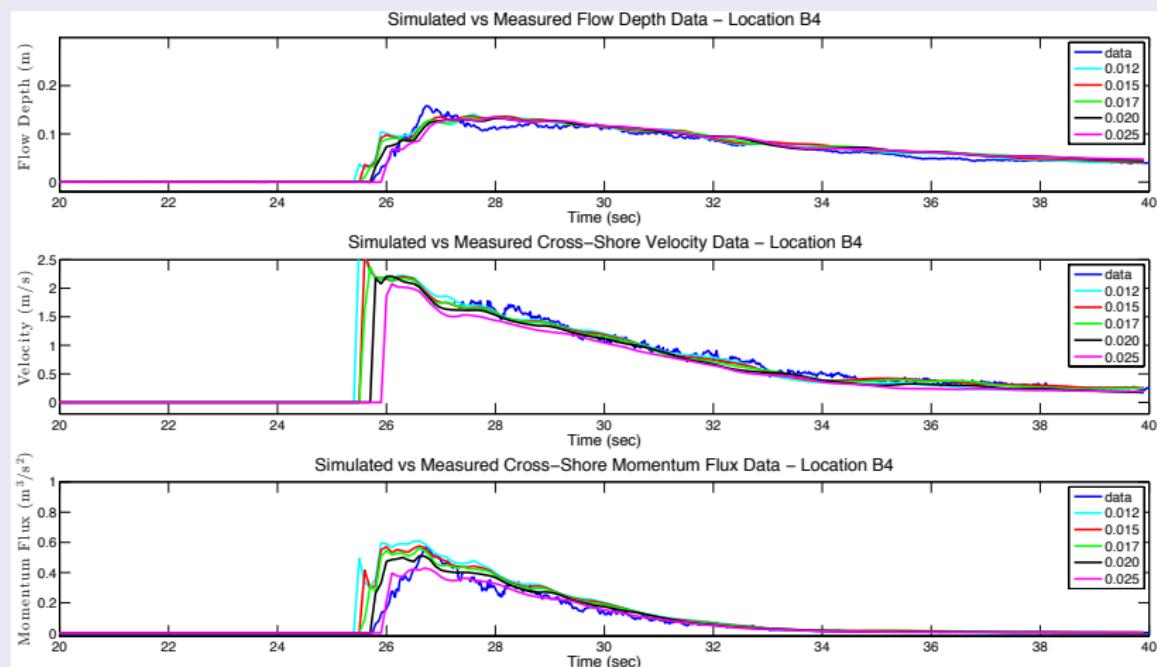
# Benchmark Problem 4 - Seaside (Oregon)

## Simulated vs Measured Data comparison at B1



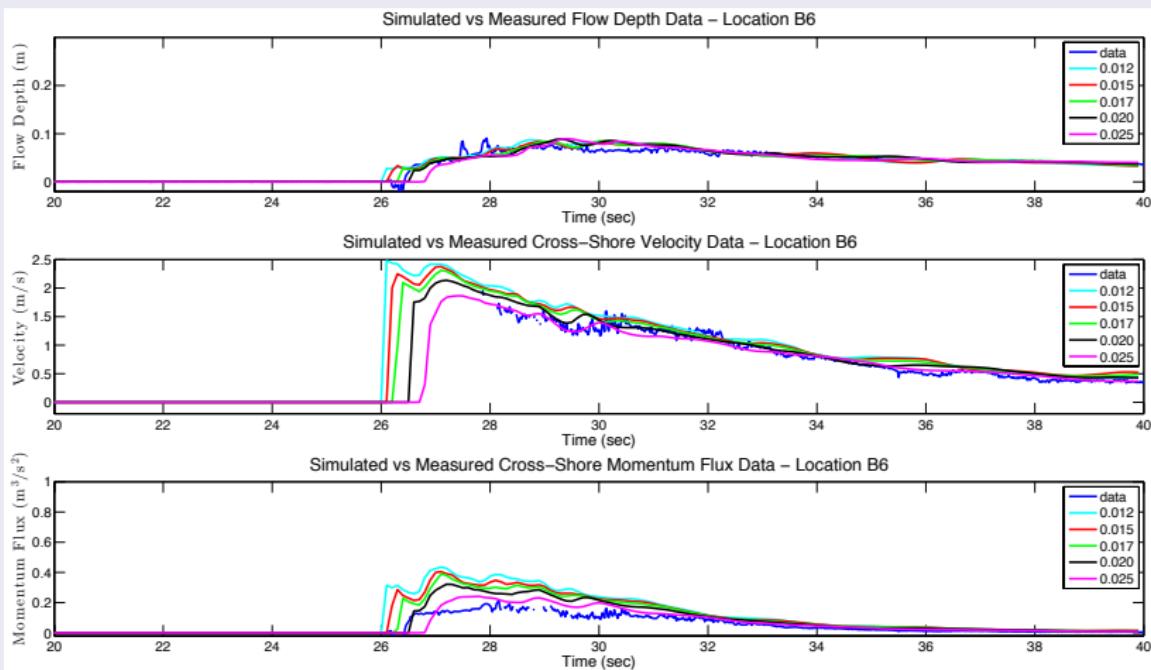
# Benchmark Problem 4 - Seaside (Oregon)

## Simulated vs Measured Data comparison at B4



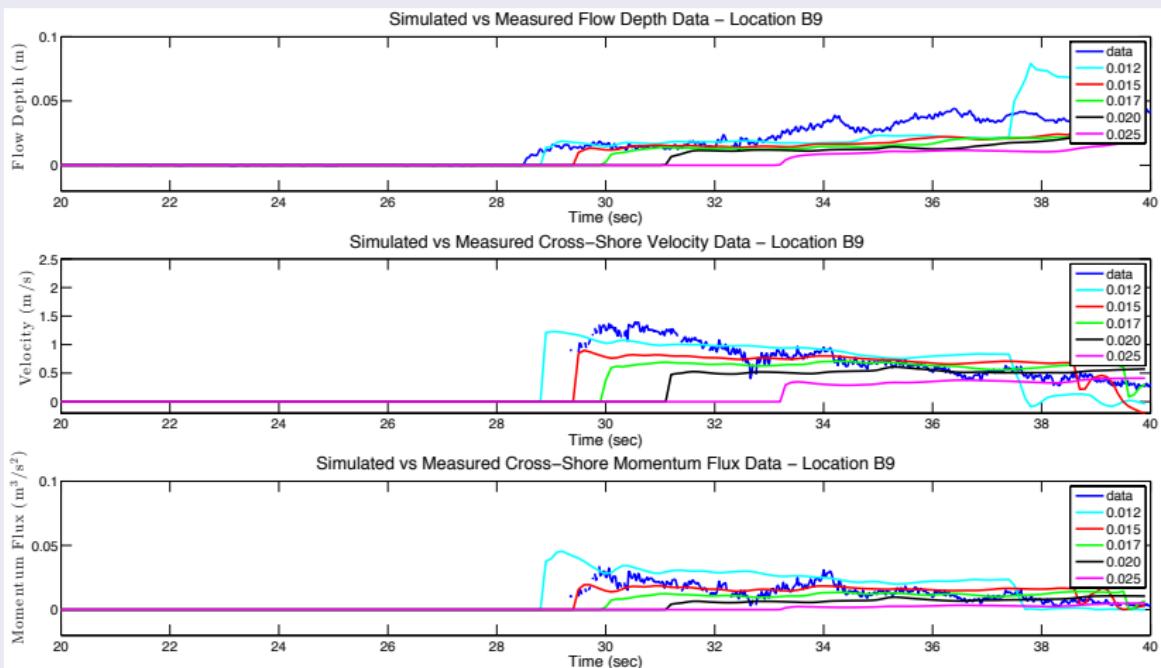
# Benchmark Problem 4 - Seaside (Oregon)

## Simulated vs Measured Data comparison at B6



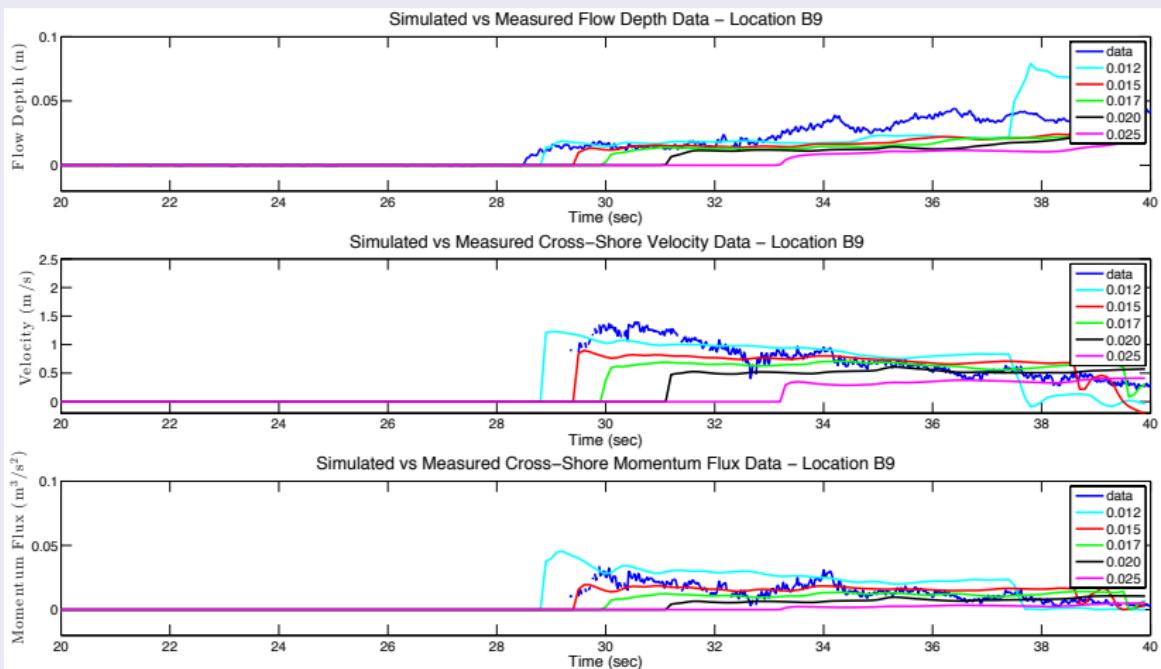
# Benchmark Problem 4 - Seaside (Oregon)

## Simulated vs Measured Data comparison at B9



# Benchmark Problem 4 - Seaside (Oregon)

## Simulated vs Measured Data comparison at B9



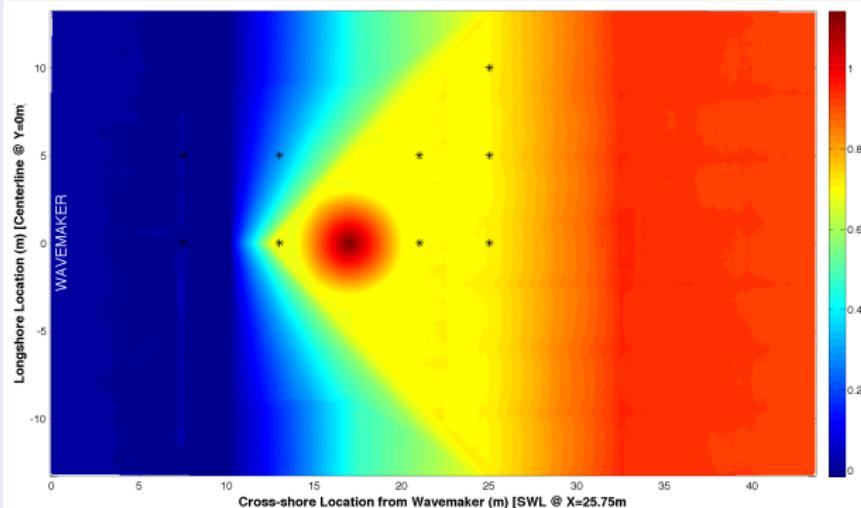
# Benchmark Problem 5

## Setup

- Single solitary wave
- Triangular shaped shelf with an island
- Free surface information
- Velocity information

# Benchmark Problem 5

## Setup - Bathymetry



## Bathymetric Data

- Approx. Domain:  $[-0.1, 44.6] \times [-13, 13]$  in meters ( $43.744 \times 26.554$  m)
- Data Resolution:  $\Delta x = 0.0438$  m -  $\Delta y = 0.0266$  m
- Mesh:  $1,000 \times 1,000$

# Benchmark Problem 5

## Model Set-up

- Extended domain  $[-9, 44.6] \times [-13, 13]$
- Initial Condition:
  - Imposed surface elevation (soliton) from Tonelli and Petti (2009):

$$\eta(x, t = 0) = A \operatorname{sech} \left[ (x - x_0) \sqrt{3A/(4H^3)} \right]$$

- Velocity Correction:

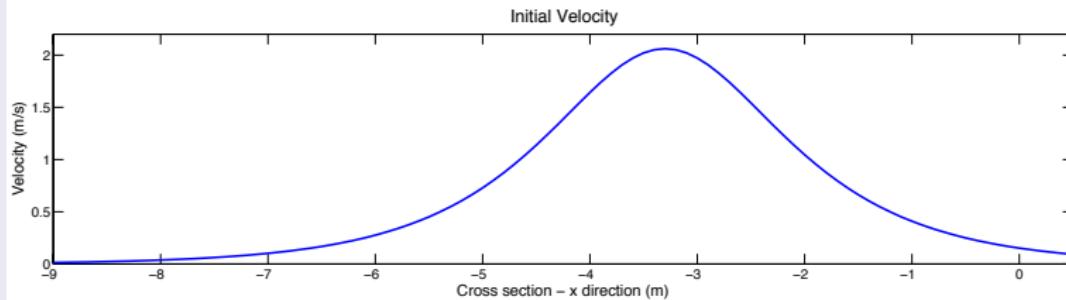
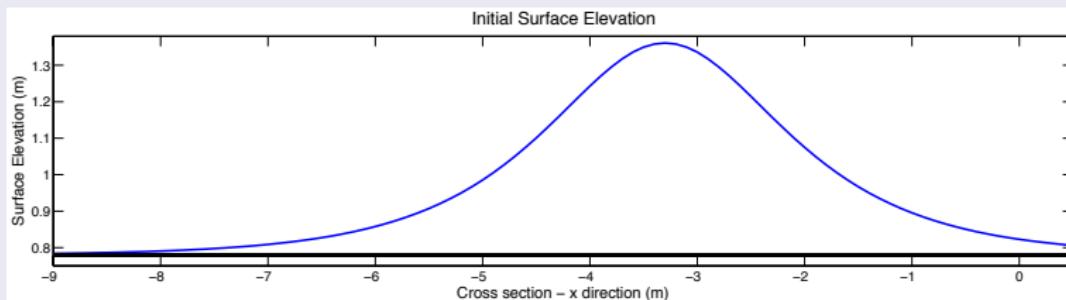
$$u(x, 0) = \eta(x, 0) \sqrt{gH/H}$$

with  $x_0 = -3.3$  m;  $A = 0.39$  m;  $H = 0.78$  m;  $g = 9.81$  m/s.

- Initial condition:
  - $h(x, y, 0) = \eta(x, 0) + 0.78$ ,
  - $q_x(x, y, 0) = h(x, y, 0) u(x, 0)$
  - $q_y = 0.0$
- Time of simulation: 20 s

# Benchmark Problem 5

## Setup - Initial Condition



# Benchmark Problem 5

## What we have done

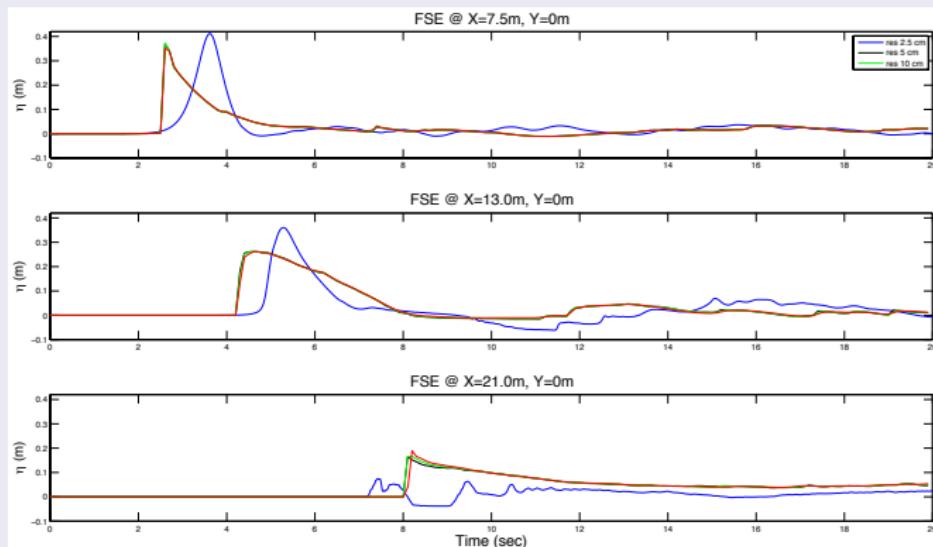
- SW non-dispersive
  - Test order (2<sup>nd</sup> and 3<sup>rd</sup>)
  - Mesh resolution (2.5 cm, 5 cm, 10 cm)
  - Friction (from 0.005 to 0.035)
- SW Dispersive (beta version)
  - 3<sup>rd</sup> order
  - Resolution 10 cm (490×260)
  - Friction (from 0.005 to 0.035)

## Some preliminary conclusions

- Dispersion is mandatory
- Friction is mostly felt in the points behind the obstacle (more if just behind)

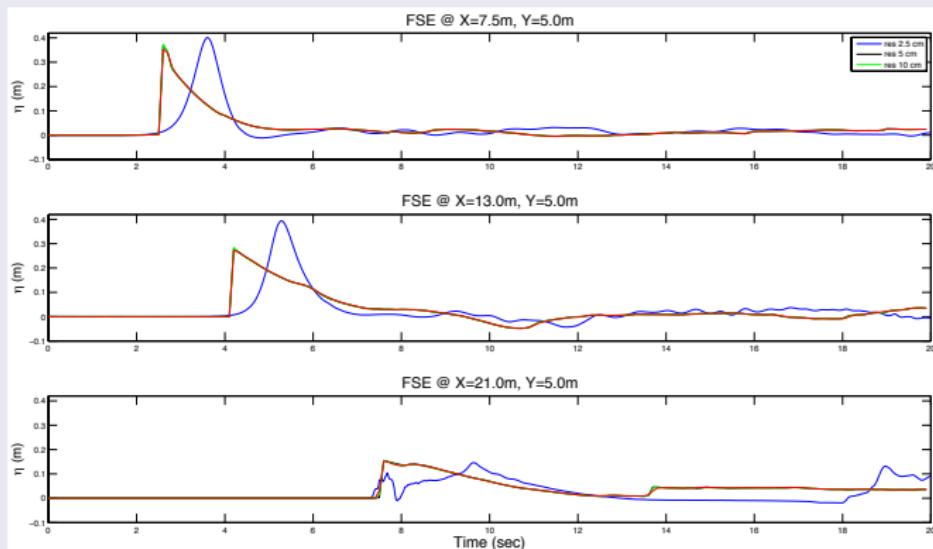
## Benchmark Problem 5. Mesh resolution

SW non-dispersive - **Three resolutions** (2.5 cm, 5 cm, 10 cm) - 3<sup>rd</sup> order - Fric 0.025



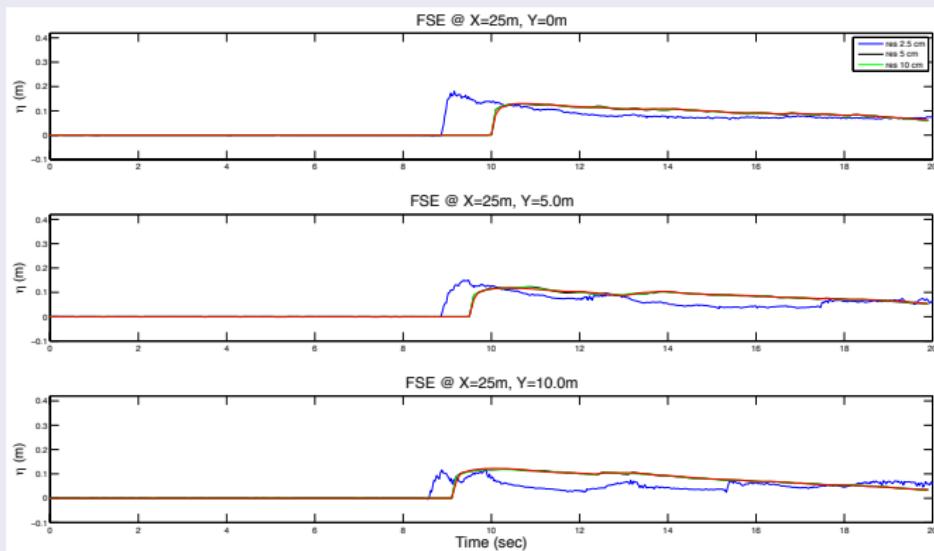
## Benchmark Problem 5. Mesh resolution

SW non-dispersive - **Three resolutions** (2.5 cm, 5 cm, 10 cm) - 3<sup>rd</sup> order - Fric 0.025



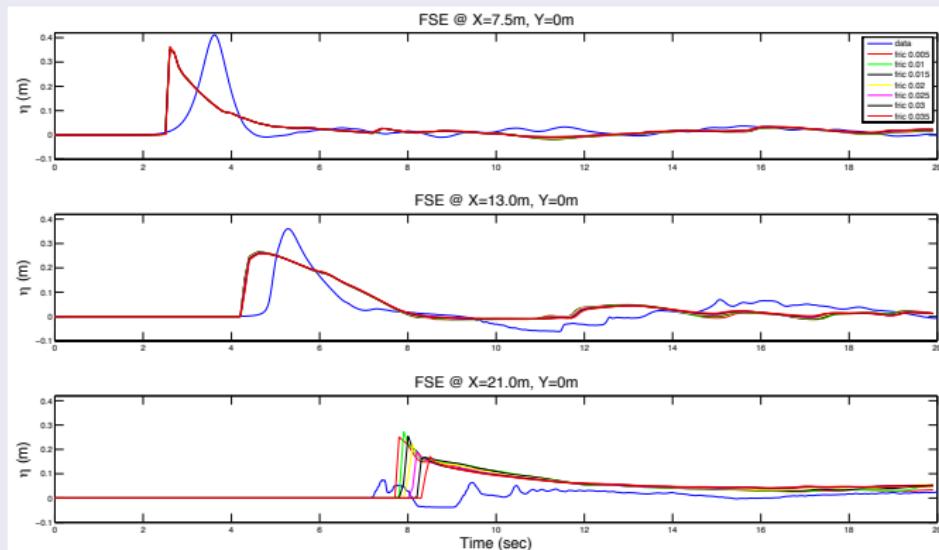
# Benchmark Problem 5. Mesh resolution

SW non-dispersive - **Three resolutions** (2.5 cm, 5 cm, 10 cm) - 3<sup>rd</sup> order - Fric 0.025



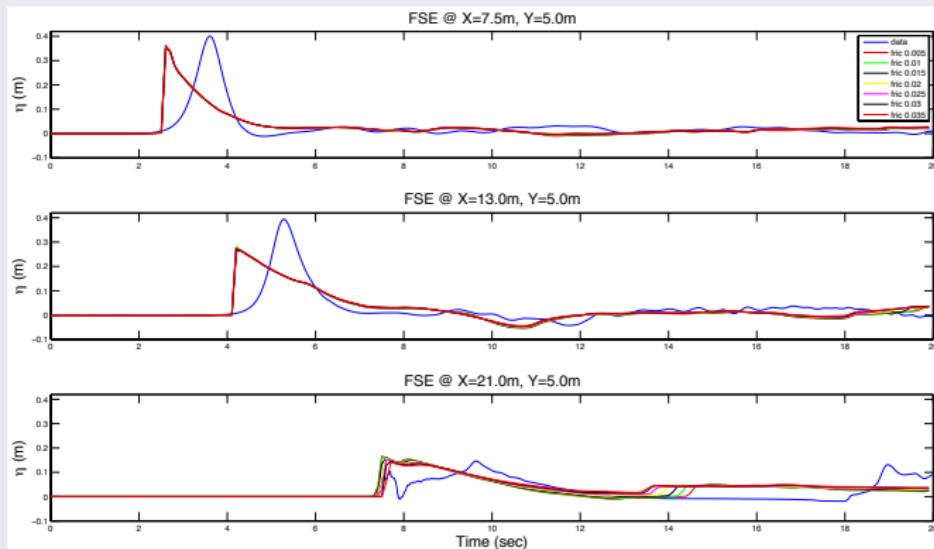
# Benchmark Problem 5 - Sensitivity to friction

SW non-dispersive - 3<sup>rd</sup> order - Res 10 cm - Varying friction



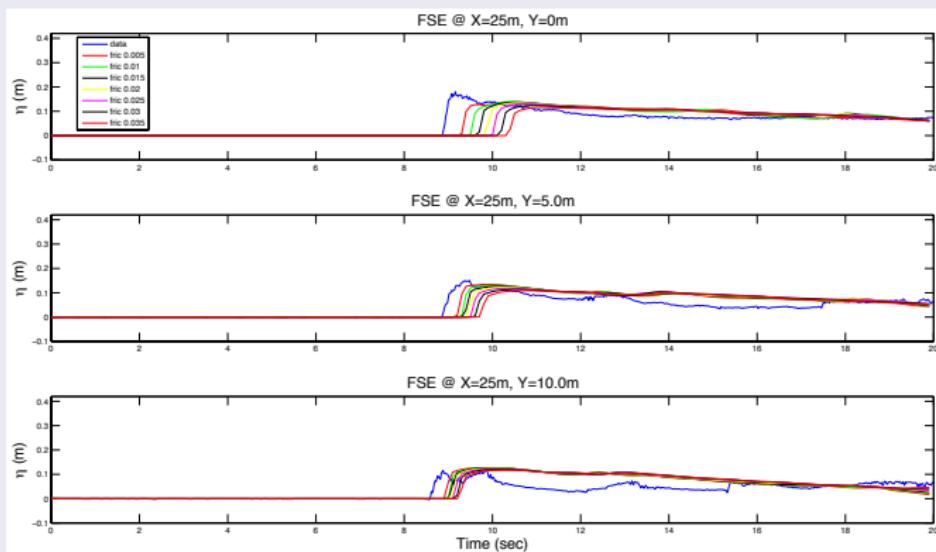
# Benchmark Problem 5 - Sensitivity to friction

SW non-dispersive - 3<sup>rd</sup> order - Res 10 cm - Varying friction



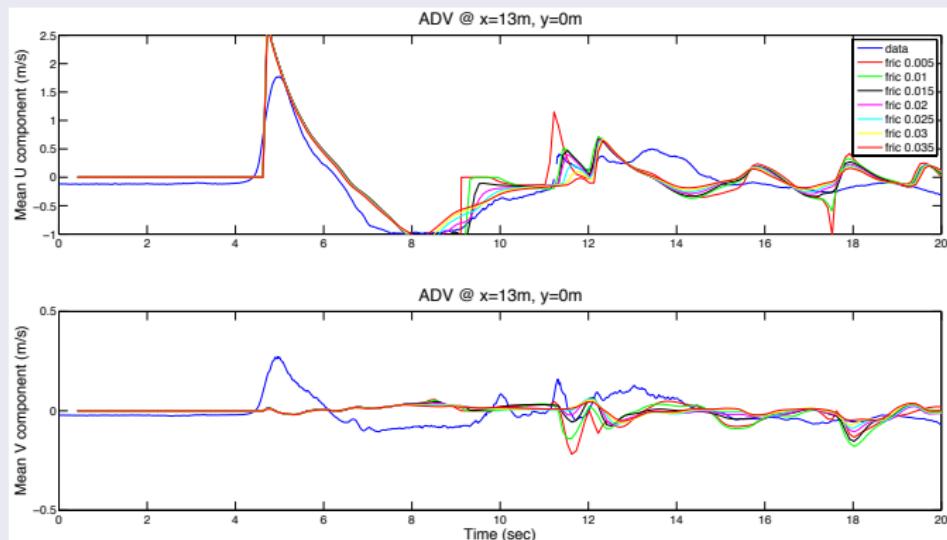
# Benchmark Problem 5 - Sensitivity to friction

SW non-dispersive - 3<sup>rd</sup> order - Res 10 cm - Varying friction



# Benchmark Problem 5. Dispersion - Sensitivity to friction

SW non-dispersive - 3<sup>rd</sup> order - Res 10 cm - Varying friction



## Benchmark Problem 5 - SW Dispersive

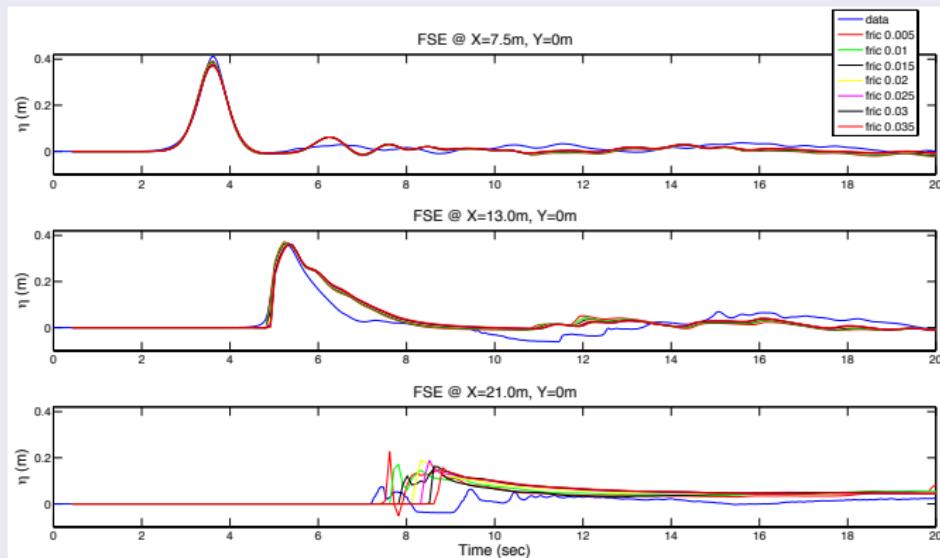
### Dispersion model - Madsen and Sorensen (1992)

- Dispersion coefficient: 1/21
- Breaking wave criteria (based on Kazolea, Delis and Synolakis, 2014).  
Dispersion is locally applied when:

- $h_i > h_{eps}$  and
- $|\partial_t \eta_i| < \gamma \sqrt{g h_i}$  with  $\gamma = 0.65$
- $(\partial_x \eta_i)^2 + (\partial_y \eta_i)^2 < \tan^2(\phi_c)$  with  $\phi_c = 33^\circ$

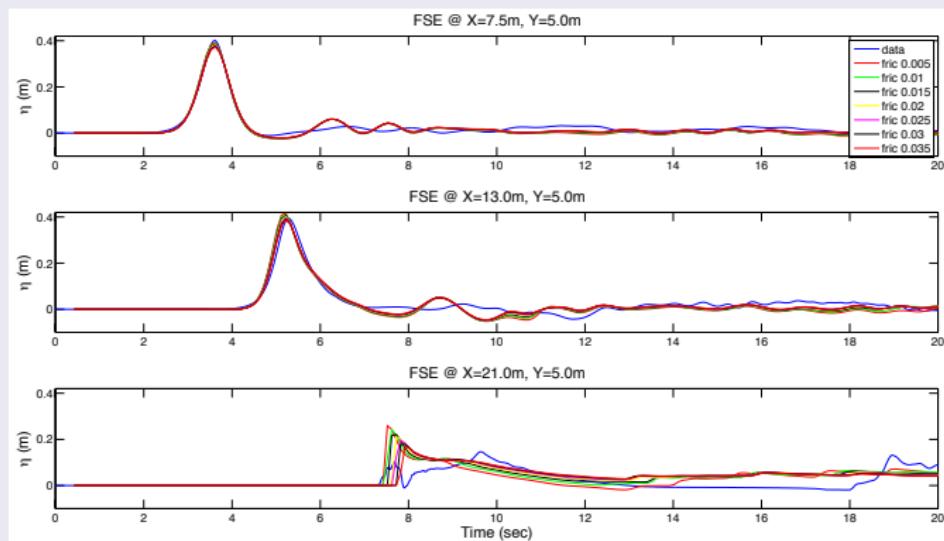
# Benchmark Problem 5. Dispersion - Sensitivity to friction

Dispersive SW - 3<sup>rd</sup> order - Res 10 cm - Varying friction



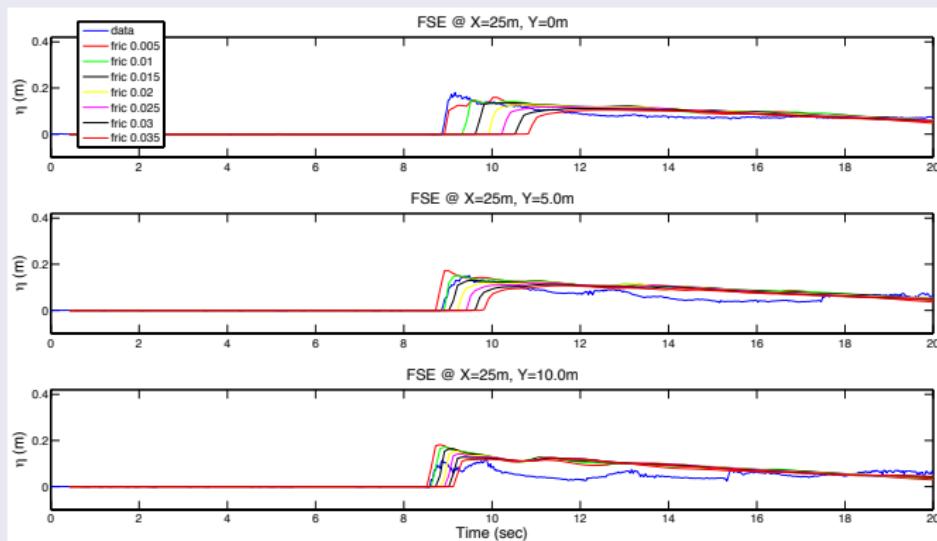
# Benchmark Problem 5. Dispersion - Sensitivity to friction

Dispersive SW - 3<sup>rd</sup> order - Res 10 cm - Varying friction



# Benchmark Problem 5. Dispersion - Sensitivity to friction

Dispersive SW - 3<sup>rd</sup> order - Res 10 cm - Varying friction



# Benchmark Problem 5. Dispersion - Varying friction

Dispersive SW - 3<sup>rd</sup> order - Res 10 cm - Varying friction

